

ANNOTATED AH RELATIONSHIPS SHEET

First derivative of displacement = velocity

$$v = \frac{ds}{dt}$$

velocity (ms⁻¹) = rate (s⁻¹) of change of displacement (m)

Second derivative of displacement = acceleration

First derivative of velocity = acceleration

$$a = \frac{dv}{dt} = \frac{d^2s}{dt^2}$$

acceleration (ms⁻²) = rate (s⁻¹) of change of velocity (ms⁻¹)

$$v = u + at$$

final velocity (ms⁻¹) = initial velocity (ms⁻¹) + acceleration (ms⁻²) × time (s)

$$s = ut + \frac{1}{2} at^2$$

displacement = initial velocity × time + $\frac{1}{2}$ × acceleration (ms⁻²) × time² (s²)

$$v^2 = u^2 + 2as$$

final velocity² (ms⁻¹)² = initial velocity² (ms⁻¹)² + 2 × acceleration (ms⁻²) × displacement (m)

First derivative of angular displacement = angular velocity

$$\omega = \frac{d\theta}{dt}$$

angular velocity (ms⁻¹) = rate (s⁻¹) of change of angular displacement (rad)

Second derivative of angular displacement = angular acceleration

First derivative of angular velocity = angular acceleration

$$a = \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2}$$

angular acceleration (rad s⁻²) = rate (s⁻¹) of change of angular velocity (rad s⁻¹)

Equation for motion for uniform angular acceleration

$$\omega = \omega_o + at$$

final angular velocity (rad s⁻¹) = initial angular velocity (rad s⁻¹) + angular acceleration (rad s⁻²) × time (s)

Equation for motion for uniform angular acceleration

$$\omega^2 = \omega_0^2 + 2a\theta$$

$$\text{final angular velocity}^2 = \text{initial angular velocity}^2 + 2 \times \text{angular acceleration} \times \text{angular displacement}$$

$$(\text{rad s}^{-1})^2 = (\text{rad s}^{-1})^2 + 2 \times (\text{rad s}^{-2}) \times (\text{rad})$$

Equation for motion for uniform angular acceleration

$$\theta = \omega_0 t + \frac{1}{2} a t^2$$

$$\text{angular displacement} = \text{initial angular velocity} \times \text{time} + \frac{1}{2} \times \text{angular acceleration} \times \text{time}^2$$

$$(\text{rad}) = (\text{rad s}^{-1}) \times (\text{s}) + \frac{1}{2} \times (\text{rad s}^{-2}) \times (\text{s})^2$$

To convert from angular quantity to linear equivalent. Angles must be in radians

$$s = r\theta$$

$$\text{linear distance} = \text{radius} \times \text{angular displacement}$$

$$(\text{m}) = (\text{m}) \times (\text{rad})$$

To convert from angular quantity to linear equivalent.

$$v = r\omega$$

$$\text{tangential velocity} = \text{radius} \times \text{angular velocity}$$

$$(\text{m s}^{-1}) = (\text{m}) \times (\text{rad s}^{-1})$$

To convert from angular quantity to linear equivalent

$$a_t = r a$$

$$\text{tangential acceleration} = \text{radius} \times \text{angular acceleration}$$

$$(\text{m s}^{-2}) = (\text{m}) \times (\text{rad s}^{-2})$$

Converts between angular velocity and period **NB $2\pi \text{ rad} = 1 \text{ revolution}$**

$$\omega = \frac{2\pi}{T}$$

$$\text{angular velocity (rad s}^{-1}\text{)} = \frac{2\pi}{\text{Period (s)}}$$

$$\text{angular frequency (rad s}^{-1}\text{)} = \frac{2\pi}{\text{Period (s)}}$$

Converts between angular velocity, frequency

$$\omega = 2\pi f$$

$$\text{angular velocity (rad s}^{-1}\text{)} = 2\pi \times \text{frequency (Hz)}$$

$$\text{angular frequency (rad s}^{-1}\text{)} = 2\pi \times \text{frequency (Hz)}$$

Radial or centripetal acceleration for uniform speed in a circle or radius r

$$a_r = \frac{v^2}{r} = r\omega^2$$

$$\text{radial acceleration} \frac{(m s^{-2})}{(m s^{-2})} = \frac{\text{tangential speed}^2 (m s^{-1})^2}{\text{radius of the circular motion} (m)} = \text{radius of the circular motion} (m) \times \text{angular velocity}^2 (rad s^{-1})^2$$

Centripetal (central) force is the unbalanced force acting towards the centre of a circle

$$F = \frac{mv^2}{r} = mr\omega^2$$

$$\text{Centripetal Force} \frac{(N)}{(N)} = \frac{\text{mass} (kg) \times \text{tangential speed}^2 (m s^{-1})^2}{\text{radius of the circular motion} (m)} = \text{mass} (kg) \times \text{radius of the circular motion} (m) \times \text{angular velocity}^2 (rad s^{-1})^2$$

Moment of inertia

$$I = \Sigma mr^2$$

Moment of inertia (kg m²) = Sum of (the mass of each particle (kg) × (distance from the axis of rotation)² (m)²)
NB the equation for individual shapes of rigid bodies around a point of rotation is given in the relationships sheet.

Torque is also known as the moment of force (or the turning effect of a force)

$$\tau = Fr$$

$$\text{torque} \frac{(Nm)}{(Nm)} = \frac{\text{Force} (N)}{(N)} \times \text{distance between the axis of rotation and force} (m)$$

For this equation the force perpendicular to the axis of rotation, you might need to find the component of force acting perpendicular to the axis of rotation.

Torque, moment of inertia and angular acceleration.

$$\tau = Ia$$

$$\text{torque} (Nm) \text{ or } (kg m^2 s^{-2}) = \text{Moment of inertia} (kg m^2) \times \text{angular acceleration} (rad s^{-2})$$

Angular momentum of a particle

$$L = mvr = mr^2\omega$$

$$\text{angular momentum of a particle} \frac{(kg m^2 s^{-1})}{(kg m^2 s^{-1})} = \frac{\text{mass} (kg)}{(kg)} \times \frac{\text{linear velocity} (m s^{-1})}{(m s^{-1})} \times \text{distance to the turning point} (m)$$

$$\text{angular momentum} \frac{(kg m^2 s^{-1})}{(kg m^2 s^{-1})} = \frac{\text{mass} (kg)}{(kg)} \times \frac{\text{distance to turning point}^2 (m)^2}{(m)^2} \times \text{angular velocity} (rad s^{-1})$$

Angular momentum of a rigid body

$$L = I\omega$$

$$\text{angular momentum} \frac{(kg m^2 s^{-1})}{(kg m^2 s^{-1})} = \frac{\text{Moment of inertia} (kg m^2)}{(kg m^2)} \times \text{angular velocity} (rad s^{-1})$$

Rotational Kinetic Energy of a rigid body

$$E_{k(\text{rotational})} = \frac{1}{2} I \omega^2$$

$$\text{Rotational kinetic energy (J)} = \frac{1}{2} \times \frac{\text{Moment of inertia (kg m}^2\text{)}}{\text{(kg m}^2\text{)}} \times \frac{\text{(angular velocity)}^2}{\text{(rad s}^{-1}\text{)}^2}$$

For objects rolling down a slope

$$E_p = E_{k(\text{translational})} + E_{k(\text{rotational})}$$

$$\text{Loss in gravitational potential energy (J)} = \text{gain in translational kinetic energy (J)} + \text{gain in rotational kinetic energy (J)}$$

NB this assumes no slipping and no energy losses due to friction

Universal Law of Gravitation

$$F = \frac{GMm}{r^2}$$

$$\text{Gravitational Force (N)} = \frac{\text{Universal gravitational Constant (m}^3\text{kg}^{-1}\text{s}^{-2}) \times \text{Mass}_1\text{(kg)} \times \text{Mass}_2\text{(kg)}}{\text{separation distance}^2 \text{ (m}^2\text{)}}$$

NB The Universal Gravitational Constant = $6.67 \times 10^{-11} \text{ m}^3\text{kg}^{-1}\text{s}^{-2}$ The separation distance is from the centre to centre of the masses.

For equating the gravitational force providing the central force to keep objects in orbit

$$F = \frac{GMm}{r^2} = \frac{mv^2}{r} = mr\omega^2 = mr \left(\frac{2\pi}{T} \right)^2$$

$$\text{gravitational Force (N)} = \frac{\text{Universal gravitational Constant (m}^3\text{kg}^{-1}\text{s}^{-2}) \times \text{Mass}_1\text{(kg)} \times \text{Mass}_2\text{(kg)}}{\text{separation distance}^2 \text{ (m}^2\text{)}} =$$

$$= \text{Centripetal Force (N)} = \frac{\text{mass (kg)} \times \text{tangential speed}^2 \text{ (m s}^{-1}\text{)}^2}{\text{radius of the circular motion (m)}}$$

$$= \text{centripetal force (kg)} = \frac{\text{mass} \times \text{radius of the circular motion (m)} \times \text{angular velocity}^2}{\text{(kg)} \quad \text{(m)} \quad \text{(rad s}^{-1}\text{)}^2}$$

$$= \text{Centripetal Force (N)} = \frac{\text{mass} \times \text{radius of the circular motion (m)}}{\text{(kg)} \quad \text{(m)}} \times \left(\frac{2\pi}{\text{orbital period (s)}} \right)^2$$

Gravitational potential is the work done (energy transferred) per unit mass needed to move an object from infinity to that location. As 0 J is at infinity all gravitational potentials are negative

$$V = -\frac{GM}{r}$$

$$\text{gravitational potential (J kg}^{-1}\text{)} = -\frac{\text{Universal Gravitational Constant (m}^3\text{kg}^{-1}\text{s}^{-2}\text{)} \times \text{mass (kg)}}{\text{separation distance(m)}}$$

Gravitational potential energy is the work done (energy transferred) needed to move an object from infinity to that location. As 0 J is at infinity all gravitational potential energies are negative

$$E_p = Vm = -\frac{GMm}{r}$$

$$\text{gravitational potential energy (J)} = \text{gravitational potential (J kg}^{-1}\text{)} \times \text{mass (kg)}$$

As the gravitational potential is negative the equation is Vm and not $-Vm$!

$$\text{gravitational potential energy (J)} = -\frac{\text{Universal gravitational Constant (m}^3\text{kg}^{-1}\text{s}^{-2}\text{)} \times \text{Mass}_1\text{(kg)} \times \text{Mass}_2\text{(kg)}}{\text{separation distance(m)}}$$

Escape velocity is the minimum speed required for a free, non-propelled object to escape from the gravitational influence of a massive body, to eventually reach an infinite distance from it. As this has the number 2 in the equation it is derived from energy and not from forces.

$$v_{esc} = \sqrt{\frac{2GM}{r}}$$

$$\text{escape velocity (ms}^{-1}\text{)} = \sqrt{\frac{2 \times \text{Universal gravitational Constant (m}^3\text{kg}^{-1}\text{s}^{-2}\text{)} \times \text{Mass being escaped from (kg)}}{\text{radius of the object being escaped from (m)}}}$$

The Schwarzschild radius- the radius of the event horizon of a black hole

$$r_{\text{schwarzschild}} = \frac{2GM}{c^2}$$

$$\text{Schwarzschild radius (m)} = \frac{2 \times \text{Universal Gravitational Constant (m}^3\text{kg}^{-1}\text{s}^{-2}\text{)} \times \text{Mass of the black hole (kg)}}{\text{speed of light}^2 \text{ (ms}^{-1}\text{)}^2}$$

Apparent brightness how bright the star appears to a detector here on Earth

$$b = \frac{L}{4\pi d^2}$$

$$\text{apparent brightness (Wm}^{-2}\text{)} = \frac{\text{Luminosity (W)}}{4\pi \times \text{distance}^2\text{(m)}^2}$$

Power radiated per unit surface area from a black body

$$\frac{P}{A} = \sigma T^4$$

$$\text{Power per unit area (Wm}^{-2}\text{)} = \text{Stefan Boltzmann Constant (5.67} \times 10^{-8} \text{ Wm}^{-2} \text{ K}^4\text{)} \times \text{(temperature)}^4 \text{ (K)}^4$$

NB The Stefan Boltzmann Constant can be found on page 2 of the exam paper on the Data Sheet and is equal to $5.67 \times 10^{-8} \text{ Wm}^{-2} \text{ K}^4$

Equation for the luminosity of a star

$$L = 4\pi r^2 \sigma T^4$$

$$\text{Luminosity (Wm}^{-2}\text{)} = 4\pi \times \text{radius of the star}^2 \text{ (m)}^2 \times \text{Stefan Boltzmann Constant (5.67} \times 10^{-8} \text{ Wm}^{-2} \text{ K}^4\text{)} \times \text{Temperature}^4 \text{ (K)}^4$$

NB The Stefan Boltzmann Constant can be found on page 2 of the exam paper on the Data Sheet and is equal to $5.67 \times 10^{-8} \text{ Wm}^{-2} \text{ K}^4$

$$E = hf$$

$$\text{energy (J)} = \text{Planck's Constant (Js)} \times \text{frequency (Hz)}$$

NB Planck's constant = $6.63 \times 10^{-34} \text{ J s}$

Bohr's Quantisation of Angular Momentum

$$mvr = \frac{nh}{2\pi}$$

$$\text{mass (kg)} \times \text{velocity (ms}^{-1}\text{)} \times \text{radius (m)} = \frac{\text{no. of shell} \times \text{Planck's Constant (J s)}}{2\pi}$$

The 2π is an indication of the circular nature equalling 1 full circle. NB Planck's constant = $6.63 \times 10^{-34} \text{ J s}$

The de Broglie wavelength, when a particle behaves like a wave and this is the wavelength associated with that.

$$\lambda = \frac{h}{p}$$

$$\text{de Broglie wavelength (m)} = \frac{\text{Planck's constant (J s)}}{\text{momentum (kg ms}^{-1}\text{)}}$$

Uncertainty principle as it refers to position and momentum

$$\Delta x \Delta p_x \geq \frac{h}{4\pi}$$

$$\text{the uncertainty in position in } x \text{ direction (m)} \times \text{uncertainty in the } x \text{ component of momentum (kg ms}^{-1}\text{)} \geq \frac{\text{Planck's Constant}}{4\pi}$$

NB In some old resources this was incorrectly marked as divided by 2π as \hbar was given as \hbar

$$\text{For the minimum uncertainty the uncertainty the product in the two quantities will} = \frac{h}{4\pi}$$

Uncertainty principle as it refers to energy and time

$$\Delta E \Delta t \geq \frac{h}{4\pi}$$

$$\frac{\text{the uncertainty in energy (J)}}{\times} \frac{\text{uncertainty in the time (s)}}{\geq} \frac{\text{Planck's Constant}}{4\pi}$$

NB In some old resources this was incorrectly marked as divided by 2π as h was given as \hbar

For the minimum uncertainty the uncertainty in the product of the two quantities will = $\frac{h}{4\pi}$

Magnetic Force

$$F = qvB$$

$$\text{Magnetic Force (N)} = \text{Charge (C)} \times \text{velocity (ms}^{-1}\text{)} \times \text{magnetic induction (T)}$$

This occurs where F and B are perpendicular, if they are not some trigonometry is required. $F = qvB \sin \theta$

Centripetal Force

$$F = \frac{mv^2}{r}$$

$$\frac{\text{Centripetal Force (N)}}{=} \frac{\text{mass (kg)} \times \text{tangential speed}^2 \text{(m s}^{-1}\text{)}^2}{\text{radius of the circular motion (m)}}$$

Proof for an object moving in SHM, and equation for force on a spring.

$$F = -ky$$

$$\text{Force (N)} = - \text{constant (Nm}^{-1}\text{)} \times \text{distance (m)}$$

The negative sign indicates the Force (and hence acceleration) is in the opposite direction to the displacement. Other units are possible but remember these quantities do have units

Converts between angular velocity, frequency and period

$$\omega = 2\pi f = \frac{2\pi}{T}$$

$$\text{angular frequency (rad s}^{-1}\text{)} = 2\pi \times \text{frequency (Hz)} = \frac{2\pi}{\text{Period (s)}}$$

NB $2\pi \text{ rad} = 1 \text{ revolution}$

Definition of S.H.M

$$a = \frac{d^2y}{dt^2} = -\omega^2 y$$

$$\frac{\text{acceleration (ms}^{-2}\text{)}}{=} \text{second derivative of displacement} = \frac{-\text{angular frequency}^2 \text{(rad s}^{-1}\text{)}^2}{\times} \text{displacement from rest position (m)}$$

Solution to SHM equation

Sine function occurs when $y=0$ and $t=0$, cosine function occurs when $y=A$ at $t=0$

$$y = A \cos \omega t \text{ or } y = A \sin \omega t$$

$$\text{displacement (m)} = \text{Amplitude(m)} \times \cosine \text{ angular frequency (rad s}^{-1}\text{)} \times \text{time (s)}$$

or

$$\text{displacement (m)} = \text{Amplitude(m)} \times \text{sine angular frequency (rad s}^{-1}\text{)} \times \text{time (s)}$$

Velocity of a particle undergoing SHM

$$v = \pm \omega \sqrt{(A^2 - y^2)}$$

$$\text{velocity (ms}^{-1}\text{)} = \pm \text{angular frequency (rad s}^{-1}\text{)} \times \sqrt{(\text{Amplitude}^2(\text{m})^2 - \text{displacement}^2(\text{m})^2)}$$

$$\text{NB } v_{\text{max}} \text{ occurs when } y = 0 \therefore v_{\text{max}} = \pm \omega A$$

Kinetic energy of a particle undergoing SHM

$$E_k = \frac{1}{2} m \omega^2 (A^2 - y^2)$$

$$\text{kinetic energy (J)} = \frac{1}{2} \times \text{mass(kg)} \times \text{angular frequency}^2 \text{ (rad s}^{-1}\text{)}^2 \times (\text{Amplitude}^2(\text{m})^2 - \text{displacement}^2(\text{m})^2)$$

NB E_k is at a maximum when $y = 0$ and zero when $y = A$

$$E_{k(\text{max})} = \frac{1}{2} m \omega^2 A^2$$

Potential energy of a particle undergoing SHM

$$E_p = \frac{1}{2} m \omega^2 y^2$$

$$\text{potential energy (J)} = \frac{1}{2} \times \text{mass(kg)} \times \text{angular frequency}^2 \text{ (rad s}^{-1}\text{)}^2 \times \text{displacement}^2(\text{m})^2$$

NB The sum of E_p and E_k remains constant

E_p is maximum when $y = A$ and zero when $y = 0$

Energy of a wave

$$E = kA^2$$

$$\text{Energy of a wave (J)} = \text{constant (Jm}^{-2}\text{)} \times \text{amplitude}^2(\text{m})^2$$

Other equivalent units are possible, but the quantities do have units

Travelling Wave Equation

$$y = A \sin 2\pi \left(ft - \frac{x}{\lambda} \right)$$

$$\text{displacement (m)} = \text{Amplitude (m)} \times \text{sine} \times 2 \times \pi \left(\text{frequency (Hz)} \times \text{time (s)} - \frac{\text{distance (m)}}{\text{wavelength (m)}} \right)$$

Lengths could be in units other than m but would need to be stated, the default position is metres

A wave travelling in the positive direction (left to right) has a negative sign in the equation, a wave travelling in the negative direction (right to left) has a positive in the equation.

Check out the various combinations of this equation where 2π could be multiplied out, a number can appear on the top which would equal $1/\lambda$, and $2\pi f$ can be replaced with ω .

It must be a travelling wave as the value of y changes with time.

$$y = A \sin 2\pi f \left(t - \frac{x}{f\lambda} \right)$$

$$y = A \sin 2\pi f \left(t - \frac{x}{v} \right)$$

$$y = A \sin \omega \left(t - \frac{x}{v} \right)$$

$$y = A \cos \omega \left(t - \frac{x}{v} \right)$$

Phase difference or phase angle between two positions on a travelling wave.

$$\phi = \frac{2\pi x}{\lambda}$$

$$\text{phase angle (rad)} = \frac{2 \times \pi \times \text{distance between the two positions (m)}}{\text{wavelength (m)}}$$

An equation which governs whether waves in materials travelling different routes will be in phase or out of phase.

$$\text{opd} = n \times \text{gpd}$$

$$\text{optical path difference (m)} = \text{refractive index} \times \text{geometric path difference (m)}$$

Conditions for constructive and destructive interference

$$\text{opd} = m\lambda \text{ or } \left(m + \frac{1}{2} \right) \lambda \text{ where } m = 0, 1, 2, \dots$$

$$\text{optical path difference (m)} = \text{a whole number of wavelength (m)} \text{ or } \text{a whole number of wavelength (m)} + \frac{1}{2} \text{ wavelength (m)}$$

$$\left(m + \frac{1}{2} \right) \lambda = \text{destructive interference}$$

$$m\lambda = \text{constructive interference}$$

Fringe separation for a thin wedge

$$\Delta x = \frac{\lambda l}{2d}$$

$$\text{fringe separation (m)} = \frac{\text{wavelength (m)} \times \text{wedge length (m)}}{2 \times \text{wedge thickness (m)}}$$

Beware, in a few questions only the distance between a certain number of fringes is given and this is (n-1) for the fringe separation, eg the distance between 11 fringes is 2.0×10^{-4} m. This is 10 fringe separations so $\Delta x = 2.0 \times 10^{-5}$ m

Non- reflection lens coating thickness

$$d = \frac{\lambda}{4n}$$

$$\text{coating thickness (m)} = \frac{\text{wavelength of light to be reduced (m)}}{4 \times \text{refractive index of the lens coating}}$$

Fringe spacing for Young's Double Slit which only applies when $D \gg \Delta x$

$$\Delta x = \frac{\lambda D}{d}$$

$$\text{fringe separation (m)} = \frac{\text{wavelength (m)} \times \text{distance from the slits to screen (m)}}{\text{slit spacing (m)}}$$

Beware, sometimes the distance between a certain number of fringes is given and this is n-1 for the fringe separation

Brewster Angle or polarising angle formula

$$n = \tan i_p$$

$$\text{refractive index} = \tan \text{ of the polarising angle (}^\circ \text{ or rad)}$$

Coulomb's Inverse Square Law

$$F = \frac{Q_1 Q_2}{4\pi\epsilon_0 r^2}$$

$$\text{Electrostatic Force (N)} = \frac{\text{Charge on point charge 1 (C)} \times \text{charge on point charge 2 (C)}}{4 \times \pi \times \text{permittivity of free space (Fm}^{-1}\text{)} \times \text{separation of the two charges}^2 \text{ (m)}^2}$$

Like charges will repel, opposite charges will attract

ϵ_0 is the permittivity of free space and is $8.85 \times 10^{-12} \text{ Fm}^{-1}$

$$\frac{1}{4\pi\epsilon_0} \approx 9 \times 10^9$$

Electric Potential

$$V = \frac{Q}{4\pi\epsilon_0 r}$$

$$\text{Electric potential (V)} = \frac{\text{Magnitude of the charge (C)}}{4 \times \pi \times \text{permittivity of free space (Fm}^{-1}) \times \text{distance from the charge (m)}}$$

$$\epsilon_0 \text{ is the permittivity of free space and is } 8.85 \times 10^{-12} \text{ Fm}^{-1} \quad \frac{1}{4\pi\epsilon_0} \approx 9 \times 10^9$$

Electric field strength

$$E = \frac{Q}{4\pi\epsilon_0 r^2}$$

$$\text{Electric field strength (NC}^{-1}) = \frac{\text{Magnitude of the charge (C)}}{4 \times \pi \times \text{permittivity of free space (Fm}^{-1}) \times \text{separation of the two charges}^2 \text{ (m)}^2}$$

$$\epsilon_0 \text{ is the permittivity of free space and is } 8.85 \times 10^{-12} \text{ Fm}^{-1} \quad \frac{1}{4\pi\epsilon_0} \approx 9 \times 10^9$$

Use for the definition of Electric field strength

$$F = QE$$

$$\text{Electric Force (N)} = \text{magnitude of the charge (C)} \times \text{Electric field strength (NC}^{-1})$$

Relationship for a uniform electric field / parallel plates

$$V = Ed$$

$$\text{Electric potential (V)} = \text{Electric field strength (NC}^{-1}) \times \text{distance (m)}$$

Work done moving a charge through a potential difference.

$$W = QV$$

$$\text{work done (J)} = \text{magnitude of the charge (C)} \times \text{potential difference (V)}$$

$$E_k = \frac{1}{2}mv^2$$

$$\text{kinetic energy (J)} = \frac{1}{2} \times \text{mass (kg)} \times \text{speed}^2 \text{ (m s}^{-1})^2$$

Magnetic induction at a perpendicular distance from an "infinite" straight current carrying conductor.

$$B = \frac{\mu_0 I}{2\pi r}$$

$$\text{Magnetic Induction (T)} = \frac{\text{Permeability of free space (Hm}^{-1}) \times \text{current (A)}}{2 \times \pi \times \text{distance (m)}}$$

$$\mu_0 = 4\pi \times 10^{-7} \text{ Hm}^{-1}$$

Force on a current carrying conductor in a magnetic field

$$F = IlB \sin \theta$$

$$\text{Magnetic Force (N)} = \text{Current (A)} \times \text{length (m)} \times \text{magnetic induction (T)} \times \sin \left(\text{angle between I and B (}^\circ \text{ or rad)} \right)$$

Derive from $F = IlB \sin \theta$

$$F = qvB$$

$$\text{Electric Force (N)} = \text{magnitude of the charge (C)} \times \text{velocity of the charge (ms}^{-1}) \times \text{magnetic induction (T)}$$

The time constant is the time required to charge the capacitor, through the resistor, from an initial charge voltage of zero to approximately 63.2% of the value of an applied DC voltage, or to discharge the capacitor through the resistor to approximately 36.8% of its initial charge voltage.

$$\tau = RC$$

$$\text{time constant (s)} = \text{Resistance of series resistor (}\Omega\text{)} \times \text{Capacitance (F)}$$

Reactance (opposition to A.C.) of a capacitor. V and I may either both be peak or r.m.s.

$$X_c = \frac{V}{I}$$

$$\text{Capacitive reactance (}\Omega\text{)} = \frac{\text{voltage (V)}}{\text{current (A)}}$$

Reactance (opposition to A.C.) of a capacitor.

$$X_c = \frac{1}{2\pi fC}$$

$$\text{Capacitive reactance (}\Omega\text{)} = \frac{1}{2 \times \pi \times \text{frequency (Hz)} \times \text{Capacitance (F)}}$$

$$\varepsilon = -L \frac{dI}{dt}$$

induced e.m.f (V) = -inductance(H) × rate of change of current (As⁻¹)

The negative sign indicates the induced e.m.f opposes the change causing it. ε is also a negative and the two negatives cancel.

Energy stored in the magnetic field of an inductor

$$E = \frac{1}{2} LI^2$$

energy stored in the magnetic field of an inductor (J) = $\frac{1}{2}$ × inductance(H) × current (A)²

Reactance (opposition to A.C.) of an inductor. V and I may either both be peak or r.m.s.

$$X_L = \frac{V}{I}$$

inductive reactance (Ω) = $\frac{\text{voltage (V)}}{\text{current (A)}}$

Reactance (opposition to A.C.) of an inductor.

$$X_L = 2\pi fL$$

inductive reactance (Ω) = 2 × π × frequency (Hz) × inductance (H)

Equation to calculate the speed of light and all electromagnetic radiations in a vacuum.

$$c = \frac{1}{\sqrt{\varepsilon_0 \mu_0}}$$

speed of light in a vacuum (ms⁻¹) = $\frac{1}{\sqrt{\text{permittivity of free space (Fm}^{-1}) \times \text{permeability of free space (Hm}^{-1})}}$

$\mu_0 = 4\pi \times 10^{-7} \text{ Hm}^{-1}$, ε_0 is the permittivity of free space and is $8.85 \times 10^{-12} \text{ Fm}^{-1}$

A method for combining uncertainties in a single measurement

$$\Delta W = \sqrt{\Delta X^2 + \Delta Y^2 + \Delta Z^2}$$

Total uncertainty in W is equal to the square root of the square of the uncertainties in X, Y and Z

NB the units of X, Y and Z are the units of the measurement

A method of combining fractional (or percentage) uncertainties in different variables.

$$\frac{\Delta W}{W} = \sqrt{\left(\frac{\Delta X}{X}\right)^2 + \left(\frac{\Delta Y}{Y}\right)^2 + \left(\frac{\Delta Z}{Z}\right)^2}$$

Fractional uncertainty in W is equal to the square root of the square of the fractional uncertainties in X, Y and Z

A method of calculating an uncertainty raised to a power

$$\left(\frac{\Delta W^n}{W^n}\right) = n \left(\frac{\Delta W}{W}\right)$$

The fractional uncertainty in W raised to power n is n times the fractional uncertainty in W

$$d = \bar{v}t$$

distance (m) = average speed (ms⁻¹) × time (s)

$$s = \bar{v}t$$

displacement (m) = average velocity (ms⁻¹) × time (s)

$$v = u + at$$

final velocity (ms⁻¹) = initial velocity (ms⁻¹) + acceleration (ms⁻²) × time (s)

$$s = ut + \frac{1}{2} at^2$$

displacement = initial velocity × time + $\frac{1}{2}$ × acceleration (ms⁻²) × time² (s²)

$$v^2 = u^2 + 2as$$

final velocity² (ms⁻¹)² = initial velocity² (ms⁻¹)² + 2 × acceleration (ms⁻²) × displacement (m)

$$s = \frac{1}{2}(v + u)t$$

displacement (m) = $\frac{1}{2}$ × (final velocity (ms⁻¹) + initial velocity (ms⁻¹)) × time (s)

$$F = ma$$

force (N) = mass (kg) × acceleration (ms⁻²)

$$W = mg$$

weight (N) = mass (kg) × gravitational field strength (N kg⁻¹)

$$E_w = Fd$$

work done (J) = force (N) × distance (m)

$$E_p = mgh$$

gravitational potential energy (J) = mass (kg) × gravitational field strength (N kg⁻¹) × vertical height (m)

$$E_k = \frac{1}{2}mv^2$$

kinetic energy (J) = $\frac{1}{2}$ × mass (kg) × speed² (ms⁻¹)²

$$P = \frac{E}{t}$$

power (W) = $\frac{\text{energy (J)}}{\text{time (s)}}$

$p = mv$ <p><i>momentum (kgms⁻¹) = mass(kg) × velocity (ms⁻¹)</i></p>
$Ft = mv - mu$ <p><i>Impulse (Ns) = mass (kg) × final velocity (ms⁻¹) – mass (kg) × initial velocity (ms⁻¹)</i> <i>Impulse (Ns) = change in momentum (kg ms⁻¹)</i></p>
$F = G \frac{m_1 m_2}{r^2}$ <p><i>Force (N) = Universal gravitational Constant (m³kg⁻¹s⁻²) $\frac{\text{Mass}_1(\text{kg}) \times \text{Mass}_2(\text{kg})}{\text{separation distance}^2 (\text{m}^2)}$</i></p> <p>NB The Universal Gravitational Constant = 6.67 × 10⁻¹¹ m³kg⁻¹s⁻²</p>
$t' = \frac{t}{\sqrt{1 - \left(\frac{v}{c}\right)^2}}$ <p><i>relativistic time (s) = $\frac{\text{time (s)}}{\sqrt{1 - \left(\frac{\text{speed (ms}^{-1}\text{)}}{\text{speed of light in vacuum (ms}^{-1}\text{)}}\right)^2}}$</i></p> <p>NB time can be in other units as this is a ratio, but both times must be in the same unit. c = 3.0 × 10⁸ ms⁻¹</p>
$l' = l \sqrt{1 - \left(\frac{v}{c}\right)^2}$ <p><i>relativistic length (m) = length (m) × $\sqrt{1 - \left(\frac{\text{speed (ms}^{-1}\text{)}}{\text{speed of light in vacuum (ms}^{-1}\text{)}}\right)^2}$</i></p> <p>c = 3.0 × 10⁸ ms⁻¹</p>
$f_o = f_s \left(\frac{v}{v \pm v_s} \right)$ <p><i>frequency observed (Hz) = frequency of source (Hz) × $\left(\frac{\text{speed of sound (ms}^{-1}\text{)}}{\text{speed of sound } \pm \text{ velocity of source (ms}^{-1}\text{)}} \right)$</i></p> <p>ADD when the object moves AWAY from the observer and TAKE AWAY (subtract) when the object comes TOWARDS the observer</p>

$z = \frac{\lambda_{\text{observed}} - \lambda_{\text{rest}}}{\lambda_{\text{rest}}}$ <p>Redshift (no unit) = $\frac{\text{observed wavelength (m)} - \text{rest wavelength (m)}}{\text{rest wavelength (m)}}$</p>
$z = \frac{v}{c}$ <p>Redshift (no unit) = $\frac{\text{recessional velocity (ms}^{-1}\text{)}}{\text{speed of light in vacuum (ms}^{-1}\text{)}}$</p>
$v = H_0 d$ <p>recessional velocity (ms⁻¹) = Hubble's Constant (s⁻¹) × distance from galaxy to observer (m)</p> <p><i>NB for this course the Hubble Constant H₀ is given as 2.3 × 10⁻¹⁸ s⁻¹</i></p>
$W = QV$ <p>Work done moving a charge across a p.d. (J) = electrical charge (C) × voltage (V)</p>
$E = mc^2$ <p>Energy (J) = mass (kg) × speed of light squared (ms⁻¹)²</p> <p><i>NB the speed of light squared is equal to 9.0 × 10¹⁶ m²s⁻²</i></p>
$E = hf$ <p>energy (J) = Planck's Constant (Js) × frequency (Hz)</p> <p><i>NB Planck's constant = 6.63 × 10⁻³⁴ Js</i></p>
$E_k = hf - hf_0$ <p>Kinetic Energy (J) = (Planck's Constant (Js) × incident frequency (Hz)) - (Planck's Constant (Js) × threshold frequency (Hz))</p> <p><i>NB Planck's constant = 6.63 × 10⁻³⁴ Js</i></p> <p><i>hf₀ is also known as the work function (J), hf is the energy of the incident photon (J)</i></p>
$E_2 - E_1 = hf$ <p>most excited energy(J) - least excited energy (J) = Planck's Constant (Js) × frequency (Hz)</p>
$T = \frac{1}{f}$ <p>Period (s) = $\frac{1}{\text{Frequency (Hz)}}$</p>
$v = f\lambda$ <p>speed (ms⁻¹) = frequency (Hz) × wavelength (m)</p>

$$d \sin \theta = m\lambda$$

Slit separation (m) × sin of angle from centre to the spot = m a whole number of wavelengths (m)

NB This equation is for constructive interference

$$n = \frac{\sin \theta_1}{\sin \theta_2}$$

Refractive index = $\frac{\text{sine of the angle in vacuum/air}}{\text{sine of the angle in the material}}$

$$\frac{\sin \theta_1}{\sin \theta_2} = \frac{\lambda_1}{\lambda_2} = \frac{v_1}{v_2}$$

Refractive index = $\frac{\text{sine of the angle in vacuum/air}}{\text{sine of the angle in the material}} = \frac{\text{wavelength (air)(m)}}{\text{wavelength (material)(m)}} = \frac{\text{speed (air) (ms}^{-1}\text{)}}{\text{speed (material)(ms}^{-1}\text{)}}$

refractive index = ratio of wavelengths in vacuum/air and material

refractive index = ratio of the speeds in $\frac{\text{vacuum}}{\text{air}}$ and the material

This formula really applies to material 1 being a vacuum, but there is not much difference between the refractive indexes of air and a vacuum ∴ we assume for Higher they have the same value.

$$\sin \theta_c = \frac{1}{n}$$

Sine of the critical angle = $\frac{1}{\text{refractive index}}$

The critical angle is the angle in the material when the angle in air is 90°

$$I = \frac{k}{d^2}$$

irradiance (Wm⁻²) = $\frac{\text{constant (W)}}{\text{distance}^2(\text{m}^2)}$

This is more easily understood as

irradiance(Wm⁻²) × distance²(m²) = constant value (W)

$$I = \frac{P}{A}$$

irradiance (Wm⁻²) = $\frac{\text{power (W)}}{\text{area (m}^2\text{)}}$

$$V_{rms} = \frac{V_{peak}}{\sqrt{2}}$$

root mean square A. C. voltage (V) = $\frac{\text{peak voltage (V)}}{1.414}$

$$I_{rms} = \frac{I_{peak}}{\sqrt{2}}$$

$$\text{root mean square A.C. current (A)} = \frac{\text{peak current (A)}}{1.414}$$

$$Q = It$$

$$\text{Charge (C)} = \text{current (A)} \times \text{time (s)}$$

This is better explained as current is the rate of flow of charge $(I = \frac{Q}{t})$

$$V = IR$$

$$\text{Voltage (V)} = \text{Current (A)} \times \text{Resistance } (\Omega)$$

$$P = IV = I^2R = \frac{V^2}{R}$$

$$\text{Power (W)} = \text{current (A)} \times \text{voltage (V)} = \text{current}^2 (\text{A}^2) \times \text{Resistance } (\Omega) = \frac{\text{Voltage}^2 (\text{V}^2)}{\text{Resistance } (\Omega)}$$

For resistors in series

$$R_T = R_1 + R_2 + \dots$$

$$\text{total resistance } (\Omega) = \text{resistance}_1 (\Omega) + \text{resistance}_2 (\Omega) + \dots$$

For resistors in parallel

$$\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \dots$$

$$\frac{1}{\text{total resistance } (\Omega)} = \frac{1}{\text{resistance}_1 (\Omega)} + \frac{1}{\text{resistance}_2 (\Omega)} + \dots$$

$$E = V + Ir$$

$$\text{e.m.f (V)} = \text{terminal potential difference (V)} + \text{current (A)} \times \text{internal resistance } (\Omega)$$

This can also be written as

$$E = I(R + r) \quad \text{or} \quad E = IR + Ir$$

I is the total current in the circuit, r is in series with the combined circuit resistance

$$V_1 = \left(\frac{R_1}{R_1 + R_2} \right) V_s$$

$$\text{voltage across component 1 in potential divider (V)} = \left(\frac{\text{resistance}_1 (\Omega)}{\text{total resistance } (\Omega)} \right) \times \text{supply voltage (V)}$$

For resistances in series (potential divider circuits)

$$\frac{V_1}{V_2} = \frac{R_1}{R_2}$$

Ratio of the voltages in series = ratio of the resistance in series

$$\frac{\text{Voltage across resistor 1 (V)}}{\text{voltage across resistor 2 (V)}} = \frac{\text{resistance of resistor 1 } (\Omega)}{\text{resistance of resistor 2 } (\Omega)}$$

$$C = \frac{Q}{V}$$

$$\text{Capacitance (F)} = \frac{\text{Charge (C)}}{\text{Voltage (V)}}$$

$$E = \frac{1}{2} QV = \frac{1}{2} CV^2 = \frac{1}{2} \frac{Q^2}{C}$$

$$\text{Energy stored in capacitor (J)} = \frac{1}{2} \times \text{charge stored in capacitor (C)} \times \text{voltage across capacitor (V)}$$

$$\text{Energy stored in capacitor (J)} = \frac{1}{2} \times \text{capacitance (F)} \times \text{voltage across capacitor}^2 (\text{V})^2$$

$$\text{Energy stored in capacitor (J)} = \frac{1}{2} \times \frac{(\text{charge stored in capacitor})^2 (\text{C}^2)}{\text{voltage across capacitor (V)}}$$

$$\text{Path difference} = m\lambda \text{ or } \left(m + \frac{1}{2}\right)\lambda, \text{ where } m = 0, 1, 2 \dots$$

$$\text{Path difference (m)} = \text{whole number of wavelengths (constructive interference)}$$

$$\text{path difference (m)} = \text{whole number of wavelengths} + \frac{1}{2} \text{ a wavelength (destructive interference)}$$

$$\text{Random Uncertainty} = \frac{\text{Max value} - \text{min value}}{\text{number of values}} \quad \text{or } \Delta R = \frac{R_{\text{max}} - R_{\text{min}}}{n}$$

NB for the random uncertainty in a value the units of the random uncertainty are the same as for the quantity you are finding the uncertainty for.

$$\text{Random Uncertainty (units of the quantity)} = \frac{\text{Max value} - \text{min value}}{\text{number of values}}$$