

2022

AH Physics Compendium



J Hargreaves 1/1/2022

Data Sheet

DATA SHEET

COMMON PHYSICAL QUANTITIES

Quantity	Symbol	Value	Quantity	Symbol	Value
Quantity Gravitational acceleration on Earth Radius of Earth Mass of Earth Mass of Moon Radius of Moon Mean Radius of Moon Orbit Solar radius Mass of Sun	$Symbol \\ g \\ R_{\rm E} \\ M_{\rm E} \\ M_{\rm M} \\ R_{\rm M}$	Value $9 \cdot 8 \text{ m s}^{-2}$ $6 \cdot 4 \times 10^6 \text{ m}$ $6 \cdot 0 \times 10^{24} \text{ kg}$ $7 \cdot 3 \times 10^{22} \text{ kg}$ $1 \cdot 7 \times 10^6 \text{ m}$ 3 \cdot 84 \times 10^8 \text{ m} 6 \cdot 955 \times 10^8 \text{ m} $2 \cdot 0 \times 10^{30} \text{ kg}$ $1 \cdot 5 \times 10^{11} \text{ m}$	Quantity Mass of electron Charge on electron Mass of neutron Mass of proton Mass of alpha particle Charge on alpha particle Planck's constant Permittivity of free	Symbol m _e e m _n m _p m _a h	Value 9.11 × 10^{-31} kg -1.60 × 10^{-19} C 1.675 × 10^{-27} kg 1.673 × 10^{-27} kg 6.645 × 10^{-27} kg 3.20 × 10^{-19} C 6.63 × 10^{-34} Js 8.85 × 10^{-12} Em ⁻¹
Stefan-Boltzmann constant Universal constant of gravitation	σ G	$5.67 \times 10^{-8} \text{W m}^{-2} \text{K}^{-4}$ $6.67 \times 10^{-11} \text{m}^3 \text{kg}^{-1} \text{s}^{-2}$	Permeability of free space Speed of light in vacuum Speed of sound in air	ε ₀ μ ₀ c	$4\pi \times 10^{-7} \mathrm{H m^{-1}}$ $3 \cdot 0 \times 10^8 \mathrm{m s^{-1}}$ $3 \cdot 4 \times 10^2 \mathrm{m s^{-1}}$

REFRACTIVE INDICES

The refractive indices refer to sodium light of wavelength 589 nm and to substances at a temperature of 273 K.

Substance	Refractive index	Substance	Refractive index
Diamond	2.42	Glycerol	1.47
Glass	1.51	Water	1.33
Ice	1.31	Air	1.00
Perspex	1.49	Magnesium Fluoride	1.38

SPECTRAL LINES

Element	Wavelength/nm	Colour	Element	Wavelength/nm	Colour				
Hydrogen	656 486 434	Red Blue-green Blue-violet	Cadmium	644 509 480	Red Green Blue				
397 Ultraviol		Ultraviolet	Lasers						
	389 Ultraviolet		Element	Wavelength/nm	Colour				
Sodium	589	Yellow	Carbon dioxide	9550 } 10590 }	Infrared				
			Helium-neon	633	Red				

PROPERTIES OF SELECTED MATERIALS

Substance	Density/ kg m ⁻³	Melting Point/ K	Boiling Point/K	Specific Heat Capacity/ J kg ⁻¹ K ⁻¹	Specific Latent Heat of Fusion/ J kg ⁻¹	Specific Latent Heat of Vaporisation/ J kg ⁻¹
Aluminium Copper Glass Ice Glycerol Methanol Sea Water Water Air	$\begin{array}{c} 2 \cdot 70 \times 10^{3} \\ 8 \cdot 96 \times 10^{3} \\ 2 \cdot 60 \times 10^{3} \\ 9 \cdot 20 \times 10^{2} \\ 1 \cdot 26 \times 10^{3} \\ 7 \cdot 91 \times 10^{2} \\ 1 \cdot 02 \times 10^{3} \\ 1 \cdot 00 \times 10^{3} \\ 1 \cdot 29 \end{array}$	933 1357 1400 273 291 175 264 273	2623 2853 563 338 377 373 	$\begin{array}{c} 9{\cdot}02 \times 10^2 \\ 3{\cdot}86 \times 10^2 \\ 6{\cdot}70 \times 10^2 \\ 2{\cdot}10 \times 10^3 \\ 2{\cdot}43 \times 10^3 \\ 2{\cdot}52 \times 10^3 \\ 3{\cdot}93 \times 10^3 \\ 4{\cdot}19 \times 10^3 \end{array}$	$\begin{array}{c} 3 \cdot 95 \times 10^5 \\ 2 \cdot 05 \times 10^5 \\ \dots \\ 3 \cdot 34 \times 10^5 \\ 1 \cdot 81 \times 10^5 \\ 9 \cdot 9 \times 10^4 \\ \dots \\ 3 \cdot 34 \times 10^5 \\ \dots \end{array}$	$ \begin{array}{c} $
Hydrogen Nitrogen Oxygen	9·0 × 10 ⁻² 1·25 1·43	14 63 55	20 77 90	1.43×10^4 1.04×10^3 9.18×10^2	· · · · · · · · ·	4.50×10^{3} 2.00×10^{5} 2.40×10^{4}

The gas densities refer to a temperature of 273 K and a pressure of 1.01×10^5 Pa.

Relationships Required For Higher Physics

$d = \overline{v}t$	$z = \frac{v}{c}$	$V_{rms} = \frac{V_{peak}}{\sqrt{2}}$
$s = \overline{v}t$	$v = H_0 d$	$I_{rms} = \frac{I_{peak}}{\sqrt{2}}$
v = u + at	W = QV	$T = \frac{1}{f}$
$s = ut + \frac{1}{2}at^2$	$E = mc^2$	V = IR
$v^2 = u^2 + 2as$	$I = \frac{P}{A}$	$P = IV = I^2 R = \frac{V^2}{R}$
$s = \frac{1}{2} (u + v)t$	$I = \frac{k}{d^2}$	$R_T = R_1 + R_2 + \dots$
W = mg	$I_1 d_1^2 = I_2 d_2^2$	$\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \dots$
F = ma	E = hf	$V_1 = \left(\frac{R_1}{R_1 + R_2}\right) V_S$
$E_w = Fd$	$E_k = hf - hf_0$	$\frac{V_1}{V_2} = \frac{R_1}{R_2}$
$E_p = mgh$	$v = f\lambda$	E = V + Ir
$E_k = \frac{1}{2}mv^2$	$E_2 - E_1 = hf$	$C = \frac{Q}{V}$
$P = \frac{E}{t}$	$dsin heta=m\lambda$	Q=It
p = mv	$n = \frac{\sin \theta_1}{\sin \theta_2}$	$E = \frac{1}{2}QV = \frac{1}{2}CV^{2} = \frac{1}{2}\frac{Q^{2}}{C}$
Ft = mv - mu		
$F = G \frac{m_1 m_2}{2}$	$\frac{\sin\theta_1}{\sin\theta_1} = \frac{\lambda_1}{\lambda_1} = \frac{v_1}{1}$	

$$t' = \frac{t}{\sqrt{1 - \frac{v^2}{c^2}}}$$
$$t' = l\sqrt{1 - \left(\frac{v}{c}\right)^2}$$
$$f_o = f_s\left(\frac{v}{v \pm v_s}\right)$$

$$\frac{\sin \theta_1}{\sin \theta_2} = \frac{\lambda_1}{\lambda_2} = \frac{v_1}{v_2}$$
$$\sin \theta_c = \frac{1}{n}$$

Path difference= $m\lambda$ or $(m + \frac{1}{2})\lambda$ where $m = 0, 1, 2 \dots$

random uncertainty= $\frac{\text{max. value} - \text{min. value}}{\text{number of values}}$

Relationships Required for Advanced Higher Physics

$v = \frac{ds}{dt}$	$E_{k(rotational)} = \frac{1}{2}I\omega^2$
$a = \frac{dv}{dt} = \frac{d^2s}{dt^2}$	$E_P = E_{k_{(translational)}} + E_{k_{(rotational)}}$
v = u + at	$F = \frac{GMm}{r^2}$
$s = ut + \frac{1}{2}at^2$	$F = \frac{GMm}{r^2} = \frac{mv^2}{r} = mr\omega^2 = mr\left(\frac{2\pi}{T}\right)^2$
$v^2 = u^2 + 2as$	$V = -\frac{GM}{m}$
$\omega = \frac{d\theta}{dt}$	$E_p = Vm = -\frac{GMm}{m}$
$\alpha = \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2}$	$v_{acc} = \sqrt{\frac{2GM}{2}}$
$\omega = \omega_0 + \alpha t$ $\theta = \omega_0 t + \frac{1}{2} \alpha t^2$	2GM
$\omega^{2} = \omega_{0}^{2} + \frac{2}{2}\alpha\theta$ $\omega^{2} = \omega_{0}^{2} + 2\alpha\theta$	$r_{Schwarzchild} = \frac{1}{c^2}$
$s = r\theta$	$b = \frac{1}{4\pi d^2}$
$ u = r\omega $ $ a_t = rlpha $	$\frac{P}{A} = \sigma T^4$
$\omega = 2\pi f$	$L = 4\pi r^2 \sigma T^4$
$\omega = \frac{2\pi}{T}$	E = hf nh
$a_r = \frac{v^2}{r} = r\omega^2$	$mvr = \frac{1}{2\pi}$
$F = \frac{mv^2}{mr\omega^2} = mr\omega^2$	$\lambda = \frac{h}{p}$
r $I = \sum mr^2$	$\Delta x \Delta p_x \ge \frac{h}{4\pi}$
$\tau = Fr$	$\Delta E \Delta t \geq \frac{h}{4\pi}$
au = I lpha	F = qvB
$L = mvr = mr^2\omega$	$F = \frac{mv^2}{r}$
$L = I\omega$	

F = -ky	F = QE
$\omega = 2\pi f = \frac{2\pi}{T}$	V = Ed
d^2y u^2w	W = QV
$a = \frac{1}{dt^2} = -\omega^2 y$	$E_k = \frac{1}{2}mv^2$
$y = A \sin \omega t$ or $y = A \cos \omega t$	$B = \frac{\mu_0 I}{2\pi r}$
$v = \pm \omega_{\rm V} \left(A^2 - y^2\right)$	$F = IlB\sin\theta$
$E_k = \frac{1}{2}m\omega^2(A^2 - y^2)$	F = qvB
$E_P = \frac{1}{2}m\omega^2 y^2$	au = RC
$E = kA^2$	$X_C = \frac{V}{I}$
$y = A\sin 2\pi \left(ft - \frac{x}{\lambda}\right)$	$X_{C} = \frac{1}{2 - CC}$
$\phi = \frac{2\pi x}{\lambda}$	$-2\pi fC$
$opd = n \times gpd$	$\varepsilon = -L \frac{dt}{dt}$
$opd = m\lambda$ or $\left(m + \frac{1}{2}\right)\lambda$ where $m = 0,1,2$	$E = \frac{1}{2}LI^2$
$\Delta x = \frac{\lambda l}{\lambda l}$	$X_L = \frac{V}{I}$
$\frac{2\pi}{2d}$	$X_L = 2\pi f L$
$d = \frac{\pi}{4n}$	$c = \frac{1}{\sqrt{1-1}}$
$\Delta x = \frac{\lambda D}{d}$	$\sqrt{\varepsilon_0\mu_0}$
$n = tan i_P$	$\Delta W = \sqrt{\Delta X^2 + \Delta Y^2 + \Delta Z^2}$
$F = \frac{Q_1 Q_2}{4\pi\varepsilon_0 r^2}$	$\frac{\Delta W}{W} = \sqrt{\left(\frac{\Delta X}{X}\right)^2 + \left(\frac{\Delta Y}{Y}\right)^2 + \left(\frac{\Delta Z}{Z}\right)^2}$
$V = \frac{Q}{4\pi\varepsilon_o r}$	$\left(\frac{\Delta W^n}{W^n}\right) = n\left(\frac{\Delta W}{W}\right)$
$E = \frac{Q}{4\pi\varepsilon_o r^2}$	

Additional relationships

Circle

circumference = $2\pi r$

 $area = \pi r^2$

Sphere

 $area = 4\pi r^2$

volume = $\frac{4}{3}\pi r^3$

Trigonometry

 $sin \theta = \frac{opposite}{hypotenuse}$

$$\cos \theta = \frac{adjacent}{hypotenuse}$$

 $\tan \theta = \frac{opposite}{adjacent}$

 $sin^2 \theta + cos^2 \theta = 1$

Moment of inertia

point mass

 $I = mr^2$

rod about centre

$$I = \frac{1}{12}ml^2$$

rod about end

$$I = \frac{1}{3}ml^2$$

disc about centre

$$I = \frac{1}{2}mr^2$$

sphere about centre

$$I = \frac{2}{5}mr^2$$

Table of standard derivatives

f(x)	f'(x)
sin ax	a cos ax
cos ax	-a cos ax

Table of standard integrals

f(x)	$\int f(x) dx$
sin ax	$-\frac{1}{a}\cos ax + C$
cos ax	$\frac{1}{a}\sin ax + C$

Greek Alphabet

Upper Case Alpha Lower Case C	$\underset{\tiny{Lower Case}}{^{Upper Case}} \underset{\beta}{\overset{Beta}{B}}$	$\overset{\text{Upper Case}}{\underset{\text{Lower Case}}{F}}\Gamma$	$\overset{\text{Upper Case}}{\underset{\text{Lower Case}}{\overset{\text{Delta}}{\overset{\text{Lower Case}}{}}}}$
Upper Case E	Upper Case Z	Upper Case H	Upper Case
Epsilon	Zeta	Eta	Theta
Lower Case E	Lower Case	Lower Case N	Lower Case
Upper Case I lota	^{Upper Case} K Kappa ^{Lower Case} K	Upper Case A Lambda Lower Case A	Upper Case Mu Mu Lower Case M
Upper Case N Nu Lower Case V	Upper Case	Upper Case Omicron Lower Case	Upper Case $\prod_{Pi \ Lower Case} \pi$
Upper Case P	Upper Case \sum	Upper Case T	Upper Case Y
Rho	Sigma	Tau	Upsilon
Lower Case p	Lower Case \mathbf{O}	Lower Case T	Lower Case U
Upper Case	Upper Case X	Upper Case Ψ	Upper Case
Phi	Chi	Psi	Omega
Lower Case	Lower Case X	Lower Case Ψ	Lower Case

Periodic Table

		87 Fr 2,8,18,3 18,8,1 Franciu	55 Cs 2,8,18,1 8,1 Caesiur	Kubidiu	Rb 2,8,18,8	37	Potassiu	2,8,8,	×:	19	Sodium	7 8 1	5 1	Lithiun	2,1	5.	3	Hydroge	<u> </u>	H -	(1)	Group	
	Lar	88 Ra 12, 2,8,18,32, 18,8,2 m Radium	50 Ba 8, 2,8,18,18, 8,2 n Barium	m strontium	Sr 2,8,18,8,2	38	m Calcium	1 2,8,8,2	<mark>ព</mark> ្ឋ	nugilesiulii	ے, سرے Magnesium	28.2	12	1 Beryllium	2,2	Ве	4	n (2)]	1 Group 2	
Actinides	ıthanides	89 Ac 2,8,18,32, 18,9,2 Actinium	5/ La 2,8,18,18, 9,2 Lanthanum	Yttnum	Y 2,8,18,9,2	39	Scandium	2,8,9,2	Sc	21	(3)												
89 Ac 2,8,18,32, 18,9,2 Actinium	57 La 2,8,18, 18,9,2 Lanthanum	104 Rf 2,8,18,32, 32,10,2 Rutherfordium	/2 Hf 2,8,18,32, 10,2 Hafnium	Zirconium	Zr 2,8,18, 10,2	49	Titanium	2,8,10,2	ц:	3	(4)									Key			
90 Th 2,8,18,32, 18,10,2 Thorium	58 Ce 2,8,18, 20,8,2 Cerium	105 Db 2,8,18,32, 32,11,2 Dubnium	/3 Ta 2,8,18, 32,11,2 Tantalum	Niobium	Nb 2,8,18, 12,1	41	Vanadium	2,8,11,2	< [2 3	(5						בופנווי			Ato			_
91 Pa 2,8,18,32, 20,9,2 Protactinium	59 Pr 2,8,18,21, 8,2 Praseodymium	106 Sg 2,8,18,32, 32,12,2 Seaborgium	/4 W 2,8,18,32, 12,2 Tungsten	Molybdenum	Mo 2,8,18,13, 1	42	Chromium	2,8,13,1	<mark>ទ</mark> រ	24	(6)					Name			Symbol	omic num			Electron
92 U 2,8,18,32, 21,9,2 Uranium	60 Nd 2,8,18,22, 8,2 Neodymium	107 Bh 2,8,18,32, 32,13,2 Bohrium	/5 Re 2,8,18,32, 13,2 Rhenium	Technetium	Tc 2,8,18,13, 2	43	Manganese	2,8,13,2	Mn	3	3	Iransition								ber			Arrangei
93 Np 2,8,18,32, 22,9,2 Neptunium	61 Pm 2,8,18,23, 8,2 Promethium	108 Hs 2,8,18,32, 32,14,2 Hassium	/6 Os 2,8,18,32, 14,2 Osmium	Ruthenium	Ru 2,8,18,15, 1	44	Iron	2,8,14,2	Fe	26	(8)		1										nents of
94 Pu 2,8,18,32, 24,8,2 Plutonium	62 Sm 2,8,18,24, 8,2 Samarium	109 Mt 2,8,18,32, 32,15,2 Meitnerium	// Ir 2,8,18,32, 15,2 Iridium	Rhodium	Rh 2,8,18,16, 1	45	Cobalt	2,8,15,2	°:	3	(9)	U.	•										Element
95 Am 2,8,18,32, 25,8,2 Americium	63 Eu 2,8,18,25, 8,2 Europium	110 Ds 2,8,18,32, 32,17,1 Darmstadtium	/8 Pt 2,8,18,32, 17,1 Platinum	Palladium	Pd 2,8,18, 18,0	46	Nickel	2,8,16,2	N.	98	(10)												N
96 Cm 2,8,18,32, 25,9,2 ^{Curium}	64 Gd 2,8,18,25, 9,2 Gadolinium	111 Rg 2,8,18,32, 32,18,1 Roentgenium	79 Au 2,8,18, 32,18,1 Gold	Silver	Ag 2,8,18, 18,1	47	Copper	2,8,18,1	5 t	96	(11)												
97 Bk 2,8,18,32, 27,8,2 Berkelium	65 Tb 2,8,18,27, 8,2 Terbium	112 Cn 2,8,18,32, 32,18,2 Copernicium	80 Hg 2,8,18, 32,18,2 Mercury	Cadmium	Cd 2,8,18, 18,2	48	Zinc	2,8,18,2	Zn	в ((12)												
98 Cf 2,8,18,32, 28,8,2 Californium	66 Dy 2,8,18,28, 8,2 Dysprosium		81 Tl 2,8,18 32,18,3 Thalliur	Indium	ln 2,8,18 18,3	49	Gallium	2,8,18,	Ga	21	درەر <u>،</u> Alumini	283	≥ 13	Boron	2,3	0	5	(13)				Group	
99 Es 2,8,18,32, 29,8,2 Einsteinium	67 Ho 2,8,18,29, 8,2 Holmium		82 Pb 2,8,18 32,18,4 n Lead		, 2,8,18 18,4	50	Germaniu	3 2,8,18,	Ge	30	m Silicon	284	2 7	Carbon	2,4	0	9	(14)				3 Group	
100 Fm 2,8,18,32, 30,8,2 Fermium	68 Er 2,8,18,30, 8,2 Erbium		83 Bi 2,8,18, 1 32,18,5 Bismuth	Antimon	2,8,18, 18,5	51	ım Arsenic	4 2,8,18,2	As	tt Iolideoliu	Phoenhon	285	0 5	Nitroger	2,5	z	7	(CI)				4 Group	
101 Md 2,8,18,32, 31,8,2 Mendelevium	69 Tm 2,8,18,31, 8,2 Thulium		84 Po 2,8,18 32,18,0 Poloniur	y Telluriur	Te 2,8,18 18,6	52	Seleniur	5 2,8,18,	Se	34	L,0,0	286	n 16	1 Oxygen	2,6	0	8	(10)				5 Group	
102 No 2,8,18,32, 32,8,2 Nobelium	70 Yb 2,8,18,32, 8,2 Ytterbium		At 2,8,18, 32,18,7 Astatine	n lodine	2,8,18, 18,7	53	n Bromine	5 2,8,18,7	Br (35	Chlorine	287	2 7	Fluorine	2,7	П	9	(17)	1			5 Group	
103 Lr 2,8,18,32, 32,9,2 Lawrencium	71 Lu 2,8,18,32, 9,2 Lutetium		80 Rn 2,8,18, 32,18,8 Radon	Xenon	Xe 2,8,18, 18,8	54	Krypton	7 2,8,18,8	<u>ና</u> ፡	36 76	L,0,0	288	18	Neon	2,8	Ne	10	Helium	2	2 He	(18)	7 Group 0	

Annotated AH Relationships Sheet *First derivative of displacement = velocity* $v = \frac{ds}{dt}$ velocity $(ms^{-1}) = rate(s^{-1})of$ change of displacement (m)Second derivative of displacement = acceleration First derivative of velocity = acceleration $a = \frac{dv}{dt} = \frac{d^2s}{dt^2}$ acceleration $(ms^{-2}) = rate(s^{-1})of$ change of velocity (ms^{-1}) v = u + atfinal velocity $(ms^{-1}) = initial velocity (ms^{-1}) + acceleration (ms^{-2}) \times time (s)$ $s = ut + \frac{1}{2} at^2$ displacement = initial velocity × time + $\frac{1}{2}$ × acceleration (ms⁻²) × time² (s²) $v^2 = u^2 + 2as$ final velocity $(ms^{-1})^2 = initial velocity (ms^{-1})^2 + 2 \times acceleration (ms^{-2}) \times dispacement (m)$ First derivative of angular displacement = angular velocity $\omega = \frac{d\theta}{dt}$ angular velocity $(ms^{-1}) = rate(s^{-1})of change of angular displacement (rad)$ $a = \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2}$ angular acceleration (rad s^{-2}) = rate (s^{-1}) of change of angular velocity (rad s^{-1}) Equation for motion for uniform angular acceleration $\omega = \omega_o + at$ $\frac{final\,angular\,velocity}{(rad\,s^{-1})} = \frac{initial\,angular\,velocity}{(rad\,s^{-1})} + \frac{angular\,acceleration}{(rad\,s^{-2})} \times \frac{time}{(s)}$

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Equation for motion for <u>uniform</u> angular acceleration
$\omega^2 = \omega_o^2 + 2a\theta$
$\frac{\text{final angular velocity}^2}{(rad s^{-1})^2} = \frac{\text{initial angular velocity}^2}{(rad s^{-1})^2} + 2 \times \frac{\text{angular acceleration}}{(rad s^{-2})} \times \frac{\text{angular dispacement}}{(rad s^{-1})}$
Equation for motion for uniform angular acceleration
1
$\theta = \omega_o t + \frac{1}{2}at^2$
$\frac{angulardisplacement}{(rad)} = \frac{initialvelocity}{(rads^{-1})} \times \frac{time}{(s)} + \frac{1}{2} \times \frac{angularacceleration}{(rads^{-2})} \times \frac{time^2}{(s)^2}$
To convert from angular quantity to linear equivalent. Angles must be in radians
s = r heta
$\frac{\text{linear distance}}{(m)} = \frac{\text{radius}}{(m)} \times \frac{\text{angular displacement}}{(mad)}$
To convert from angular quantity to linear equivalent.
$v = r\omega$
$tangential velocity = radius \times angular velocity$
$(m s^{-1})$ $(m a s^{-1})$ $(rad s^{-1})$
To convert from angular quantity to linear equivalent
$a_t = ra$
tangential acceleration radius angular acceleration
$(m s^{-2}) \qquad = (m) \qquad \times \qquad (rad s^{-2})$
Converts between angular velocity, frequency and period NB 2π rad = 1 revolution
$\omega = \frac{2\pi}{T}$
angular velocity (rad s^{-1}) = $\frac{2\pi}{Period(s)}$

Converts between angular velocity, frequency and period				
$\omega=2\pi f$				
angular velocity (rad s^{-1}) = $2\pi \times frequency$ (Hz)				
Radial or centripetal acceleration for uniform speed in a circle or radius r				
$a_r = rac{v^2}{r} = r\omega^2$				
$\begin{aligned} radial \ acceleration \\ (m \ s^{-2}) \end{aligned} = \frac{tangential \ speed^2 (m \ s^{-1})^2}{radius \ of \ the \ circular \ motion \ (m)} = \frac{radius \ of \ the \ circular \ motion \ x}{(m)} \times \frac{angular \ velocity \ ^2}{(rad \ s^{-1})^2} \end{aligned}$				
Centripetal (central) force is the unbalanced force acting towards the centre of a circle				
$F = \frac{mv^2}{r} = mr\omega^2$				
$\frac{Centripetal Force}{(N)} = \frac{mass (kg) \times tangential speed^2 (m s^{-1})^2}{radius of the circular motion (m)} = \frac{mass \times radius of the circular motion}{(kg)} \times \frac{mass \times radius of the circular motion}{(m)} \times \frac{mass \times radius of the circular motion}{(rad s^{-1})^2}$				
Moment of inertia				
$I = \Sigma m r^2$ Moment of inertia (ka m ²) - Sum of (the mass of each martiale (ka) × (distance from the axis of votation) ² (m) ²)				
$Moment of there (kg m) = sum of (the mass of each particle (kg) \times (alstance from the axis of rotation) (m))$				
NB the equation for individual shapes of rigid bodies around a point of rotation is given in the relationships sheet.				
Torque is also known as the moment of force (or the turning effect of a force)				
au=Fr				
torque $(Nm) = Force(N) \times distance$ between the line of action of force and the point of rotation (m)				
au = Ia				
Torque (Nm) = Moment of inertia (kg m ²) × angular acceleration (rad s ⁻²)				

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Converts between angular velocity, frequency and period
$\omega = 2\pi f = \frac{2\pi}{\pi}$
$\frac{1}{2\pi}$
angular belocity (rad s ⁻¹) = $2\pi \times frequency$ (Hz) = $\frac{1}{Period(s)}$
NB 2π rad = 1 revolution
Definition of S.H.M
$a = \frac{d^2 y}{dt^2} = -\omega^2 y$
$\frac{acceleration}{(ms^{-2})} = second \ derivative \ of \ displacement = \frac{-angular \ frequency^2}{(rad \ s^{-1})^2} \times \frac{displacement \ from \ rest \ position}{(m)}$
Solution to SHM equation
Sine function occurs when y=0 and t=0, cosine function occurs when y=A at t=0
$y = A \cos \omega t \text{ or } y = A \sin \omega t$
displacement $(m) = Amplitude(m) \times cosine$ angular frequency $(rad s^{-1}) \times time(s)$
or
displacement $(m) = Amplitude(m) \times sine angular frequency (rad s-1) \times time (s)$
Velocity of a particle undergoing SHM
$v = \pm \omega \sqrt{(A^2 - y^2)}$
$velocity(ms^{-1}) = \pm angular frequency(rad s^{-1}) \times \sqrt{(Amplitude^2(m)^2 - displacment^2(m)^2)}$
$NB \ v_{max} \ occurs \ when \ y = 0 \ \ \cdot \ \ v_{max} = \ \pm \omega A$
Kinetic energy of a particle undergoing SHM
$E_k = \frac{1}{2}m\omega^2(A^2 - y^2)$
$kinetic\ energy\ (J) = \frac{1}{2} \times mass(kg) \times angular\ frequency^2\ (rad\ s^{-1})^2 \times (Amplitude^2(m)^2 - \ displacment^2(m)^2))$
NB Ek is at a maximum when y = 0 and zero when y = A $E_{k(max)} = \frac{1}{2}m\omega^2 A^2$



$opd = n \times gpd$				
optical path difference (m) = refractive index \times geometric path difference (m)				
Conditions for constructive and destructive interference				
$opd = m\lambda \ or\left(m+rac{1}{2} ight)\lambda$ where $m=0,1,2,$				
optical path difference = a whole number of wavelength or a whole number of wavelength $+\frac{1}{2}$ wavelength				
(m) (m) (m)				
$\left(m+\frac{1}{2}\right)\lambda = destructive interference$				
$m\lambda = constructive interference$				
Fringe separation for a thin wedge				
$\Delta r = \frac{\lambda l}{\lambda l}$				
$\frac{2n}{2d}$				
fringe separation $(m) = \frac{wavelength(m) \times wedge length(m)}{m}$				
$2 \times wedge thickness(m)$				
Beware, sometimes the distance between a certain number of fringes is given and this is n-1 for the fringe separation				
Non- reflection lens coating thickness				
$d = \frac{\lambda}{\lambda}$				
u = 4n				
coating thickness $(m) = \frac{wavelength of light to be reduced (m)}{m}$				
$4 \times refraction$ index of the lens coating				
Fringe spacing for Young's Double Slit which only applies when D>>Ax				
$\Delta x = \frac{\lambda D}{d}$				
wavelength $(m) \times distance$ from the slits to screen (m)				
$fringe separation (m) = \frac{slit spacing (m)}{slit spacing (m)}$				
Beware, sometimes the distance between a certain number of fringes is given and this is n-1 for the fringe separation				
Brewster Angle or polarising angle formula				
$n = tan i_n$				
refractive index = tan of the polarising angle (°or rad)				

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Coulomb's Inverse Square Law					
$-Q_1Q_2$					
$F = \frac{1}{4\pi\varepsilon_0 r^2}$					
$Charge on point charge 1 (C) \times charge on point charge 2 (C)$					
Electrostatic Force (N) = $\frac{1}{4 \times \pi \times \text{permitivity of free space (Fm}^{-1}) \times \text{separation of the two charges}^2 (m)^2}$					
Like charges will repel, opposite charges will attract					
ε_0 is the permittivity of free space and is 8.85 × 10 ⁻¹² Fm ⁻¹ $\frac{1}{4\pi\varepsilon_0} \approx 9 \times 10^{5}$					
Electric Potential					
V - Q					
$V = \frac{1}{4\pi\varepsilon_o r}$					
Electric notential (V) =					
$4 \times \pi \times permitivity of free space (Fm^{-1}) \times distance from the charge (m)$					
ε_o is the permitivity of free space and is 8.85 $\times 10^{-12} Fm^{-1}$ $\frac{1}{4\pi\varepsilon_o} \approx 9 \times 10^9$					
Electric field strength					
$F - \frac{Q}{Q}$					
$L = 4\pi\varepsilon_o r^2$					
$Electric field strength (NC^{-1}) Magnitude of the charge (C)$					
$4 \times \pi \times permitivity of free space (Fm^{-1}) \times separation of the two charges^2 (m)^2$					
$\epsilon_{\rm c}$ is the permitivity of free space and is 8.85 $\times 10^{-12} Fm^{-1}$ $\frac{1}{} \approx 9 \times 10^9$					
$4\pi\varepsilon_{o}$					
Use for the definition of Electric field strength					
F = QE					
$Electric Force (N) = magnitude of the charge (C) \times Electric field strength (NC^{-1})$ Relationship for a uniform electric field					
V - Ed					
V = Lu Electric notential (V) = Electric field strength (NC ⁻¹) × distance (m)					
Work done moving a charge through a potential difference.					
W = QV					
work done (J) = magnitude of the charge (C) × potential difference (V)					

$E_k = \frac{1}{2}mv^2$			
$1 - \frac{1}{1} - $			
$kinetic energy (J) = \frac{1}{2} \times mass (kg) \times speed^2 (m s^{-1})^2$			
Magnetic induction at a perpendicular distance from an "infinite" straight current carrying conductor.			
$B = \frac{\mu_0 I}{\overline{a}}$			
$2\pi r$ Dermoghility of free space (Hm^{-1}) \times support (A)			
Magnetic Induction (T) = $\frac{Permeability of free space (IIII -) \times current (A)}{2 \times - \times distance (m)}$			
$2 \times \pi \times \text{alstance}(m)$			
$\mu_0 = 4\pi \times 10^{-1} \text{ mm}$ Force on a current carrying conductor in a magnetic field			
$F = IlB \sin \theta$			
Magnetic Force Current length magnetic induction (angle between I and B)			
$(N) = (A) \times (m) \times (T) \times (o \text{ or } rad) $			
Derive from $F = IlB \sin \theta$			
F = qvB			
$\frac{Electric \ Force}{(N)} = \frac{magnitude of \ the \ charge}{(C)} \times \frac{velocity \ of \ the \ charge}{(m \ c^{-1})} \times \frac{magnetic \ induction}{(T)}$			
(N) (C) (MS^{-1}) (I)			
approximately 63.2% of the value of an applied DC voltage or to discharge the capacitor through the resistor to			
approximately 36.8% of its initial charge voltage.			
au = RC			
time constant (s) = Resistance of series resistor (Ω) × Capacitance (F)			
Reactance (opposition to a.c.) of a capacitor. V and I may either <u>both</u> be peak or r.m.s			
V V			
$X_c = \overline{I}$			
voltaae (V)			
Capacitive reactance $(\Omega) = \frac{\sigma(x)}{current(A)}$			
Reactance (opposition to a.c.) of a capacitor.			
$\mathbf{v} = 1$			
$\Lambda_c = \frac{1}{2\pi fC}$			
$Capacitive reactance(Q) = \frac{1}{2}$			
$2 \times \pi \times frequency (Hz) \times Capacitance (F)$			



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A method of combining fractional (or percentage) uncertainties in different variables.
$\frac{\Delta W}{W} = \sqrt{\left(\frac{\Delta X}{X}\right)^2 + \left(\frac{\Delta Y}{Y}\right)^2 + \left(\frac{\Delta Z}{Z}\right)^2}$
Fractional uncertainty in W is equal to the square root of the square of the fractional uncertainties in X, Y and Z
A method of calculating an uncertainty raised to a power
$\left(\frac{\Delta \boldsymbol{W}^{\boldsymbol{n}}}{\boldsymbol{W}^{\boldsymbol{n}}} ight)=\boldsymbol{n}\left(\frac{\Delta \boldsymbol{W}}{\boldsymbol{W}} ight)$
The fractional uncertainty in W raised to power n is n times the fractional uncertainty in W
$d = \overline{v}t$
distance $(m) = average speed (ms^{-1}) \times time (s)$
$s = \overline{v}t$
$displacement (m) = average \ velocity \ (ms^{-1}) \times time \ (s)$
v = u + at
$final \ velocity \ (ms^{-1}) = initial \ velocity \ (ms^{-1}) + acceleration \ (ms^{-2}) \times time \ (s)$
$s = ut + \frac{1}{2} at^2$
$displacement = initial \ velocity \ \times \ time + \frac{1}{2} \times \ acceleration \ (ms^{-2}) \times \ time^2 \ (s^2)$
$v^2 = u^2 + 2as$
final velocity $(ms^{-1})^2 = initial velocity (ms^{-1})^2 + 2 \times acceleration (ms^{-2}) \times dispacement (m)$
$s=\frac{1}{2}(\nu+u)t$
$displacement (m) = \frac{1}{2} \times (final \ velocity \ (ms^{-1}) + initial \ velocity \ (ms^{-1})) \times time \ (s)$
F = ma
$force (N) = mass (kg) \times acceleration (ms^{-2})$
W = mg
weight $(N) = mass (kg) \times gravitational field strength (N kg^{-1})$

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$E_w = Fd$					
work done $(J) = force(N) \times distance(m)$					
$E_p = mgh$					
$gravitational\ potential\ energy\ (J) =\ mass\ (kg) imes gravitational\ field\ strength\ (N\ kg^{-1}) imes vertical\ height\ (m)$					
$E_k = \frac{1}{2}mv^2$					
kinetic energy $(J) = \frac{1}{2} \times mass (kg) \times speed^2 (ms^{-1})^2$					
$P = \frac{E}{t}$					
$power(W) = \frac{energy(J)}{time(s)}$					
p = mv					
$momentum (kgms^{-1}) = mass(kg) \times velocity (ms^{-1})$					
Ft = mv - mu					
Impulse (Ns) = mass (kg) × final velocity (ms ⁻¹) – mass (kg) × initial velocity (ms ⁻¹)					
Impulse (Ns) = change in momentum (kg ms ⁻¹)					
$F = G \frac{m_1 m_2}{r^2}$					
Force (N) = Universal gravitational Constant $(m^3kg^{-1}s^{-2})$ $\frac{Mass_1(kg) \times Mass_2(kg)}{separation distance^2 (m^2)}$					
NB The Universal Gravitational Constant $= 6.67 imes 10^{-11} m^3 kg^{-1}s^{-2}$					
$t' = \frac{t}{\sqrt{1 - \left(\frac{v}{c}\right)^2}}$					
relativistic time (s) =time (s)					
$\sqrt{1 - \left(\frac{speed \ (ms^{-1})}{speed \ of \ light \ in \ vacuum \ (ms^{-1})}\right)^2}$					
NB time can be in other units as this is a ratio, but both times must be in the same unit. $c = 3.0 \times 10^8 \text{ms}^{-1}$					



$E = mc^2$
Energy $(J) = mass (kg) \times speed of light squared (ms^{-1})^2$
NB the speed of light squared is equal to 9.0 $ imes$ 10 ¹⁶ m ² s ⁻²
E = hf
$energy (J) = Planck's Constant (Js) \times frequency (Hz)$
NB Planck's constant = 6.63×10^{-34} Js
$E_k = hf - hf_o$
$\underbrace{Kinetic Energy}_{(J)} = \left(\underbrace{Planck's Constant}_{(Js)} \times \underbrace{incident frequency}_{(Hz)} \right) - \left(\underbrace{Planck's Constant}_{(Js)} \times \underbrace{threshold frequency}_{(Hz)} \right)$
NB Planck's constant = 6.63 x 10 ⁻³⁴ Js
hf_o is also known as the work function (J), hf is the energy of the incident photon (J)
$E_2 - E_1 = hf$
most excited energy(J) – least excited energy (J) = $Planck's Constant (Js) \times frequency (Hz)$
$T = \frac{1}{f}$
$Period (s) = \frac{1}{Frequency (Hz)}$
$ u = f\lambda$
$speed (ms^{-1}) = frequency (Hz) \times wavelength (m)$
$d\sin\theta = m\lambda$
Slit separation (m) × sin of angle from centre to the spot = m a whole number of wavelengths (m)
NB This equation is for constructive interference
$n = \frac{\sin \theta_1}{2}$
$n = \sin \theta_2$
$Refractive index = \frac{sine of the angle in vacuum/air}{sine of the angle in vacuum/air}$
sine of the angle in the material

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$V_1 = \left(\frac{R_1}{R_1 + R_2}\right) V_s$
$voltage \ across \ component \ 1 \ in \ potential \ divider(V) = \left(\frac{resistance_1 \ (\Omega)}{total \ resistance(\Omega)}\right) \times supply \ voltage \ (V)$
For resistances in series (potential divider circuits)
$\frac{V_1}{V_2} = \frac{R_1}{R_2}$
Ratio of the voltages in series = ratio of the resistance in series
Voltage across resistor $1(V)$ resistance of resistor $1(\Omega)$
$\overline{voltageacrossresistor2(V)} = \overline{resistanceofresistor2(\Omega)}$
$C = \frac{Q}{V}$
$Capacitance (F) = \frac{Charge (C)}{Voltage (V)}$
$E = \frac{1}{2}QV = \frac{1}{2}CV^2 = \frac{1}{2}\frac{Q^2}{C}$
Energy stored in capacitor -1 \downarrow charge stored in capacitor \downarrow voltage across capacitor
$(J) \qquad -\overline{2} \land \qquad (C) \qquad \land \qquad (V)$
Energy stored in capacitor $=\frac{1}{x}$ capacitance voltage across capacitor ²
(J) $(V)^2$ $(V)^2$
Energy stored in capacitor 1 (charge stored in capacitor) ² (C^2)
(J) $-\frac{1}{2} \times \frac{1}{voltage \ across \ capacitor(V)}$



SI Units

There is an international standard for units called the Systeme International D'Unites, SI units for short.

These consist of seven basic units, two of which we do not use in this course (the unit of luminous intensity, the candela, and the amount of substance containing a certain number of elementary particles, the mole).

The 5 basic units we use are units of mass, length, time, temperature and current. Every other unit can be expressed using a combination of these seven basic units.

<u>Quantity</u>	<u>Symbol</u>	<u>Units</u>
Mass	т	kilogram, kg
Length	l	metre, m
Time	t	second, s
Temperature	Т	degrees Celsius, Kelvin, K
Current	1	ampere, A

Prefixes

<u>Prefix</u>	<u>Symbol</u>	<u>Multiple</u>	<u>Multiple in full</u>
Peta	Р	x10 ¹⁵	x 1 000 000 000 000 000
Tera	Т	x10 ¹²	x1 000 000 000 000
Giga	G	x10 ⁹	x1 000 000 000
Mega	М	x10 ⁶	x1 000 000
Kilo	K	x10 ³	x1 000
Centi	С	x10 ⁻²	÷100
Milli	т	x10 ⁻³	÷1 000
Micro	μ	x10 ⁻⁶	÷1 000 000
Nano	n	x10 ⁻⁹	÷1 000 000 000
Pico	р	x10 ⁻¹²	÷1 000 000 000 000
femto	f	x10 ⁻¹⁵	÷1 000 000 000 000 000

Above is a table of prefixes, which you will commonly find in AH Physics.

The Physics Course

Course content

The course content includes the following areas of physics:

Rotational motion and astrophysics

The topics covered are:

- Ψ kinematic relationships
- Ψ angular motion
- Ψ rotational dynamics
- Ψ gravitation
- Ψ general relativity
- Ψ stellar physics

Quanta and waves

The topics covered are:

- ${f \Psi}$ introduction to quantum theory
- Ψ particles from space
- Ψ simple harmonic motion
- Ψ waves
- Ψ interference
- Ψ polarisation

Electromagnetism

The topics covered are:

- Ψ fields
- Ψ circuits
- Ψ electromagnetic radiation

Units, prefixes and uncertainties

The topics covered are:

 Ψ units, prefixes and scientific notation

 Ψ uncertainties

- Ψ data analysis
- Ψ evaluation and significance of experimental uncertainties

Course overview

This course consists of 32 SCQF credit points, which includes time for preparation for course assessment. The notional length of time for candidates to complete the course is 160 hours.

The course assessment has two components.

Component	Marks	Scaled mark	Duration
Component 1: question paper	155	120	3 hours
Component 2: project	30	40	see 'Course assessment' section

No		v x	Traffic Light						
ROTATIONAL MOTION AND ASTROPHYSICS									
Kinem	natic relationships		\odot	() ()	8				
1.1	I know that differential calculus notation is used to represent rate of change.		:		\odot				
1.2	I know that velocity is the rate of change of displacement with time, acceleration is the rate of change of velocity with time and acceleration is the second differential of displacement with time.		\odot	:	\odot				
1.3	I can derive the equations of motion $v = u + at$ and $s = ut + \frac{1}{2}at^2$ using calculus methods.		\odot		(<u>)</u>				
1.4	I can use calculus methods to calculate instantaneous displacement, velocity and acceleration for straight line motion with a constant or varying acceleration.		\odot		3				
1.5	I can use appropriate relationships to carry out calculations involving displacement, velocity, acceleration, and time for straight line motion with constant or varying acceleration.				$\overline{\mathbf{S}}$				
1.6	$v = \frac{ds}{dt}$ $a = \frac{dv}{dt} = \frac{d^2s}{dt^2}$ $v = u + at$ $s = ut + \frac{1}{2}at^2$ for constant acceleration only $v^2 = u^2 + 2as$		\odot	:	3				

No		v x	Traf	fic Li	ght
1.7	I know that the gradient of a curve (or a straight line) on a motion- time graph represents instantaneous rate of change, and can be found by differentiation.		:		3
1.8	I know that the gradient of a curve (or a straight line) on a displacement-time graph is the instantaneous velocity, and that the gradient of a curve (or a straight line) on a velocity-time graph is the instantaneous acceleration.		٢		3
1.9	I know that the area under a line on a graph can be found by integration.		\odot		3
1.10	I know that the area under an acceleration-time graph between limits is the change in velocity, and that the area under a velocity-time graph between limits is the displacement.		٢		3
	I can determine displacement, velocity or acceleration by the calculation of the gradient of the line on a graph or the calculation of the area under the line between limits on a graph.		٢		3
Angula	ar motion		\odot	٢	8
2.1	I can use the radian as a measure of angular displacement.		\odot		\odot
2.2	I can convert between degrees and radians.		\odot		\odot
2.3	I can use appropriate relationships to carry out calculations involving angular displacement, angular velocity, angular acceleration, and time.			:	(<u>;</u>)
2.4	$\omega = \frac{d\theta}{dt}$ $\alpha = \frac{d\omega}{dt} = \frac{d^{2}\theta}{dt^{2}}$ $\omega = \omega_{o} + \alpha t$ $\omega^{2} = \omega_{o}^{2} + 2\alpha\theta$ for constant angular acceleration only $\theta = \omega_{o}t + \frac{1}{2}\alpha t^{2}$		٢		::

No		v x	Traf	fic Li	ght
2.5	I can use appropriate relationships to carry out calculations involving angular and tangential motion.		\odot		$\overline{\mathbf{S}}$
2.6	$s = r\theta$				
	$v = r\omega$		\odot		\otimes
	$a_t = r\alpha$				
2.7	I can use appropriate relationships to carry out calculations involving constant angular velocity, period and frequency.		:		$\overline{\mathbf{S}}$
2.8	$\omega = \frac{2\pi}{T}$		0		
	$\omega = 2\pi f$		\odot		$\overline{\mathbf{O}}$
2.9	I know that a centripetal (radial or central) force acting on an object is necessary to maintain circular motion, and results in		:		$\overline{\mathbf{i}}$
	centripetal (radial or central) acceleration of the object.				
2.10	I can use appropriate relationships to carry out calculations involving centripetal acceleration and centripetal force.		\odot		$\overline{\mathbf{i}}$
2.11	$a_r = \frac{v^2}{r} = r\omega^2$				
	$F = \frac{mv^2}{r} = mr\omega^2$		\odot		\odot
Rotati	onal dynamics		0	\odot	
3.1	I know that an unbalanced torque causes a change in the angular (rotational) motion of an object.		\odot		$\overline{\mathbf{i}}$
3.2	I can define the moment of inertia of an object as a measure of its resistance to angular acceleration about a given axis.		\odot		$\overline{\mathfrak{S}}$
3.3	I know that moment of inertia depends on mass and the distribution of mass about a given axis of rotation.		\odot		$\overline{\otimes}$
3.4	I can use an appropriate relationship to calculate the moment of inertia for discrete masses.		\odot		$\overline{\otimes}$
3.5	$I = mr^2$		\odot		$\overline{\otimes}$

No		v x	Traf	fic Li	ght
3.6	I can use an appropriate relationship to calculate the moment of inertia for discrete masses.		:		$\overline{\mathfrak{S}}$
3.7	$I = \sum mr^2$		\odot		\bigotimes
3.8	I can use appropriate relationships to calculate the moment of inertia for rods, discs and spheres about given axes.		0		$\overline{\mathbf{S}}$
3.9	rod about centre $I = \frac{1}{12}ml^2$				
	rod about end $I = \frac{1}{3}ml^2$				
	disc about centre $I = \frac{1}{2}mr^2$				8
	sphere about centre $I = \frac{2}{5}mr^2$				
3.10	I can use appropriate relationships to carry out calculations involving torque, perpendicular force, distance from the axis, angular acceleration, and moment of inertia.		\odot		$\overline{\mathbf{S}}$
3.11	$\tau = Fr$ $\tau = I\alpha$		\odot		8
3.12	I can use appropriate relationships to carry out calculations involving angular momentum, angular velocity, moment of inertia, tangential velocity, mass and its distance from the axis.				\bigotimes
3.13	$L = mvr = mr^2\omega$ $L = I\omega$:		$\overline{\mathbf{S}}$
3.14	I can make a statement of the principle of conservation of angular momentum. "In the absence of external torques the total angular momentum before a collision is the same as the total angular momentum after a collision"	<u> </u>	٢		::
3.15	I can use the principle of conservation of angular momentum to solve problems.		\odot		$\overline{\mathbf{S}}$

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No		v x	Traf	fic Li	ght
3.16	I can use appropriate relationships to carry out calculations involving potential energy, rotational kinetic energy, translational kinetic energy, angular velocity, linear velocity, moment of inertia, and mass.		٢		\odot
3.17	$E_k = \frac{1}{2}I\omega^2$ or $E_{k(rotational)} = \frac{1}{2}I\omega^2$		\odot		3
3.18	$E_P = E_k (\text{translational}) + E_k (\text{rotational})$		\odot		\odot
Gravit	ation		0	0	:
4.1	I can convert between astronomical unit (AU) and metres and between light years (ly) and metres		\odot		\odot
4.2	I can define gravitational field strength as the gravitational force acting on a unit mass.		\odot		\odot
4.3	I can sketch of gravitational field lines and field line patterns around astronomical objects and astronomical systems involving two objects.		٢		3
4.4	I can use an appropriate relationship to carry out calculations involving gravitational force, masses and their separation.		٢		\odot
4.5	$F = \frac{GMm}{r^2}$:		\odot
4.6	I can use appropriate relationships to carry out calculations involving period of satellites in circular orbit, masses, orbit radius, and satellite speed.		٢		3
4.7	$F = \frac{GMm}{r^2} = \frac{mv^2}{r} = mr\omega^2 = mr\left(\frac{2\pi}{T}\right)^2$		\odot		().
4.8	I can define gravitational potential of a point in space as the work done in moving unit mass from infinity to that point		\odot		\odot
4.9	I know that the energy required to move mass between two points in a gravitational field is independent of the path taken.				\otimes

No		√x	Traf	fic Li	ght
4.10	I can use appropriate relationships to carry out calculations involving gravitational potential, gravitational potential energy, masses and their separation.		٢		\odot
4.11	$V = -\frac{GM}{r}$ $E_p = Vm = -\frac{GMm}{r}$		٢		$\overline{\mathfrak{S}}$
4.12	I can define escape velocity as the minimum velocity required to allow a mass to escape a gravitational field to infinity, where the mass achieves zero kinetic energy and maximum (zero) potential energy.		0	:	3
4.13	I can derive the relationship $v = \sqrt{\frac{2GM}{r}}$.		\odot		$\overline{\mathbf{i}}$
4.14	I can use of an appropriate relationship to carry out calculations involving escape velocity, mass and distance.		\odot		$\overline{\mathbf{o}}$
4.15	$v = \sqrt{\frac{2GM}{r}}$		\odot		\odot
Gener	al relativity		\odot	\odot	:
5.1	I know that special relativity deals with motion in inertial (non-accelerating) frames of reference and that general relativity deals with motion in non-inertial (accelerating) frames of reference		٢		3
5.2	I can state the equivalence principle (that it is not possible to distinguish between the effects on an observer of a uniform gravitational field and of a constant acceleration) and I know of its consequences		٢		3
5.3	I consider spacetime as a representation of three dimensions of space and one dimension of time.		3		$\overline{\mathfrak{S}}$
5.4	I know that general relativity leads to the interpretation that mass curves spacetime, and that gravity arises from the curvature of spacetime.			:	$\overline{\mathbf{S}}$

No		v x	Traf	fic Li	ght
5.5	I know that light or a freely moving object follows a geodesic (the shortest distance between two points) in spacetime.		\odot		\odot
5.6	I can represent world lines for objects which are stationary, moving with constant velocity and accelerating		\odot		\odot
5.7	I know that the escape velocity from the event horizon of a black hole is equal to the speed of light.		\odot		\odot
5.8	I know that, from the perspective of a distant observer, time appears to be frozen at the event horizon of a black hole.		\odot		\odot
5.9	I know that the Schwarzschild radius of a black hole is the distance from its centre (singularity) to its event horizon.		\odot		\odot
5.10	I can use an appropriate relationship to solve problems relating to the Schwarzschild radius of a black hole.		\odot		\odot
5.11	$r_{Schwarzschild} = \frac{2GM}{c^2}$:		3
Stellar	physics		0	\odot	:
6.1	I can use appropriate relationships to solve problems relating to luminosity, apparent brightness, b, distance between the observer and the star, power per unit area, stellar radius, and stellar surface temperature. (Using the assumption that stars behave as black bodies.)		\odot	:	\odot
6.2	apparent brightness $b = \frac{L}{4\pi d^2}$				
	$\frac{P}{A} = \sigma T^4$ $L = 4\pi r^2 \sigma T^4$				\odot
6.3	I know that stars are formed in interstellar clouds when gravitational forces overcome thermal pressure and cause a molecular cloud to contract until the core becomes hot enough to sustain nuclear fusion, which them provides a thermal poressure that balances the gravitational force.		\odot		\odot

No		√x	Traf	fic Li	ght
6.4	I know of the stages in the proton-proton chain (p-p chain) in stellar fusion reactions which convert hydrogen to helium. One example of a p-p chain is:		٢		3
6.5	$^{1}_{1}H + ^{1}_{1}H \rightarrow ^{2}_{1}H + ^{0}_{+1}e + \nu_{e}$				
	$^{2}_{1}H + ^{1}_{1}H \rightarrow ^{3}_{2}He + \gamma$		\odot		$\overline{\otimes}$
	${}_{2}^{3}\text{He} + {}_{2}^{3}\text{He} \rightarrow {}_{2}^{4}\text{He} + 2{}_{1}^{1}\text{H}$				
6.6	I know that the Hertzsprung-Russell (H-R) diagram is a representation of the classification of stars.		\odot		$\overline{\mathbf{S}}$
6.7	I can classify stars and position in Hertzsprung-Russell (H-R) diagram, including main sequence, giant, supergiant and white dwarf.		٢		\odot
6.8	I can use Hertzsprung-Russell (H-R) diagram to determine stellar properties, including prediction of colour of stars from their position in the H-R diagram.		Û		\odot
6.9	I know that the fusion of hydrogen occurs in the core of stars in the main sequence of a Hertzsprung-Russell (H-R) diagram.		\odot		$\overline{\mathbf{S}}$
6.10	I know that when hydrogen fusion in the core of a star supplies the energy that maintains the star's outward thermal pressure to balance inward gravitational forces. When the hydrogen in the core becomes depleted, nuclear fusion in the core ceases. The gas surrounding the core, however, will still contain hydrogen. Gravitational forces cause both the core, and the surrounding shell of hydrogen to shrink. In a star like the Sun, the hydrogen shell becomes hot enough for hydrogen fusion in the shell of the star. This leads to an increase in pressure which pushes the surface of the star outwards, causing it to cool. At this stage, the star will be in the giant or supergiant regions of a Hertzspung-Russell (H-R) diagram.		\odot	:	\odot
6.11	I know that in a star like the Sun, the core shrinks and will become hot enough for the helium in the core to begin fusion		\odot		8
6.12	I know that the mass of a star will determine its lifetime		\odot		$\overline{\boldsymbol{\otimes}}$

No		√x	Traf	fic Li	Light	
6.13	I know that every star will ultimately become a white dwarf, a neutron star or a black hole. The mass of the star will determine its eventual fate			:	$\ddot{\mathbf{x}}$	
	QUANTA AND WAVES					
Introd	uction to quantum theory		\odot	0		
7.1	I know of experimental observations that cannot be explained by classical physics, but can be explained using quantum theory:		٢		3	
7.1a	Black-body radiation curves (ultraviolet catastrophe);		\odot		\odot	
7.1b	The formation of emission and absorption spectra. ;		\odot		\odot	
7.1c	The photoelectric effect.		\odot		\odot	
7.2	I can use an appropriate relationship to solve problems involving photon energy and frequency.		\odot		\odot	
7.3	E = hf		\odot		\odot	
7.4	I know that the Bohr model of the atom in terms of the quantisation of angular momentum, the principal quantum number n and electron energy states, and how this explains the characteristics of atomic spectra.		٢		3	
7.5	I can use an appropriate relationship to solve problems involving the angular momentum of an electron and its principal quantum number.			:	3	
7.6	$mvr = \frac{nh}{2\pi}$		\odot		\odot	
7.7	I can provide a description of experimental evidence for the particle-like behaviour of 'waves' and for the wave-like behaviour of 'particles'.			:	$\overline{\mathbf{S}}$	
7.8	I can use an appropriate relationship to solve problems involving the de Broglie wavelength of a particle and its momentum.		٢		\odot	

No		√x	Traf	fic Li	ght
7.9	$\lambda = \frac{h}{p}$:		\odot
7.10	I know that it is not possible to know the position and the momentum of a quantum particle simultaneously		:		\odot
7.11	I know that it is not possible to know the lifetime of a quantum particle and the associated energy change simultaneously.		9		\odot
7.12	I can use appropriate relationships to solve problems involving the uncertainties in position, momentum, energy and time. The lifetime of a quantum particle can be taken as the uncertainty in time.		\odot	:	0:
7.13	$\Delta x \Delta p_x \ge \frac{h}{4\pi}$ $\Delta E \Delta t \ge \frac{h}{4\pi}$		3	:	ŝ
7.14	I know of implications of the Heisenberg uncertainty principle, including the concept of quantum tunnelling, in which a quantum particle can exist in a position that, according to classical physics, it has insufficient energy to occupy.		\odot		ß
Partio	cles from space		0	\odot	:
8.1	I know of the origin and composition of cosmic rays and the interaction of cosmic rays with Earth's atmosphere		\odot		\odot
8.2	I know of the composition of the solar wind as charged particles in the form of plasma.		0	::	\odot
8.3	I can explain the helical motion of charged particles in the Earth's magnetic field.		\odot		\odot
8.4	I can use appropriate relationships to solve problems involving the force on a charged particle, its charge, its mass, its velocity, the radius of its path, and the magnetic induction of a magnetic field.			::	(

No		√x	Traf	Traffic Light		
8.5	$F = qvB$ $F = \frac{mv^2}{r}$		9	:	ŝ	
Simp	le harmonic motion (SHM)		0	()	()	
9.1	I can define SHM in terms of the restoring force and acceleration proportional to, and in the opposite direction to, the displacement from the rest position.		0	:	\odot	
9.2	I can use of calculus methods to show that the expressions $y = A \sin \omega t$ and $y = A \cos \omega t$ are consistent with the definition of SHM ($a = -\omega^2 y$)		\odot		\odot	
9.3	I can derive the relationships $v = \pm \omega \sqrt{A^2 - y^2}$ and $E_k = \frac{1}{2}m\omega^2(A^2 - y^2)$.		0	:	ŝ	
9.4	I can use appropriate relationships to solve problems involving the displacement, velocity, acceleration, angular frequency, period, and energy of an object executing SHM.		\odot	:	(\mathbf{x})	
9.5	F = -ky $\omega = 2\pi f = \frac{2\pi}{T}$ $a = \frac{d^2 y}{dt^2} = -\omega^2 y$ $y = A\cos \omega t \text{ or } y = A\sin \omega t$ $v = \pm \omega \sqrt{\left(A^2 - y^2\right)}$ $E_k = \frac{1}{2}m\omega^2 \left(A^2 - y^2\right)$ $E_p = \frac{1}{2}m\omega^2 y^2$		\odot	(i)	\Im	
9.6	I know of the effects of damping in SHM (to include underdamping, critical damping and overdamping).		\odot		$\overline{\otimes}$	

No		v x	Traf	fic Li	ght
Waves			\odot	0	
10.1	I can use an appropriate relationship to solve problems involving the energy transferred by a wave and its amplitude.		\odot		\odot
10.2	$E = kA^2$		\odot		\odot
10.3	I know of the mathematical representation of travelling waves.		:		\odot
10.4	I can use appropriate relationships to solve problems involving wave motion, phase difference and phase angle.		\odot		\odot
10.5	$y = A \sin 2\pi \left(ft - \frac{x}{\lambda} \right)$ $\phi = \frac{2\pi x}{\lambda}$		٢		3
10.6	I know that stationary waves are formed by the interference of two waves, of the same frequency and amplitude, travelling in opposite directions. A stationary wave can be described in terms of nodes and antinodes.		٢		3
Interfe	erence		\odot	\odot	:
11.1	I know that two waves are coherent if they have a constant phase relationship		\odot		\odot
11.2	I know of the conditions for constructive and destructive interference in terms of coherence and phase		\odot		\odot
11.3	I can use an appropriate relationship to solve problems involving optical path difference, geometrical path difference and refractive index.		٢		3
11.4	optical path difference = $n \times$ geometrical path difference		\odot		$\overline{\mathbf{S}}$
11.5	I know that a wave experiences a phase change of π when it is travelling in a less dense medium and reflects from an interface with a more dense medium.		\odot		\odot

No		v x	Traf	fic Li	ght
11.6	I know that a wave does not experience a phase change when it is travelling in a more dense medium and reflects from an interface with a less dense medium		٢		3
11.7	I can explain interference by division of amplitude, including optical path length, geometrical path length, phase difference, optical path difference,		\odot	:	3
11.8	I know of thin film interference and wedge fringes.		\odot		\odot
11.9	light interfering by division of amplitude, I can use an ropriate relationship to solve problems involving the ical path difference between waves, wavelength and order nber.		٢		3
11.10	optical path difference = $m\lambda$ or $\left(m+\frac{1}{2}\right)\lambda$ where $m=0,1,2$		\odot		3
11.11	I know that a coated (bloomed) lens can be made non- reflective for a specific wavelength of light.		:		\odot
11.12	I can derive the relationship $d = \frac{\lambda}{4n}$ for glass lenses with a coating such as magnesium fluoride.		\odot	::	3
11.13	I can use appropriate relationships to solve problems involving interference of waves by division of amplitude		\odot		\odot
11.14	$\Delta x = \frac{\lambda l}{2d}$		\odot		\odot
11.15	$d = \frac{\lambda}{4n}$		\odot		\odot
11.16	I can explain interference by division of wavefront.		\odot		\odot
11.17	I have a knowledge of Young's slits interference.		\odot		$\overline{\ensuremath{\mathfrak{S}}}$
11.18	I can use an appropriate relationship to solve problems involving interference of waves by division of wavefront.		:		\odot
11.19	$\Delta x = \frac{\lambda D}{d}$:		$\overline{\mathbf{S}}$

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No			Traf	fic Li	ght
Polari	sation		0	0	
12.1	I know of what is meant by a plane-polarised wave.		\odot		$\overline{\ensuremath{\mathfrak{S}}}$
12.2	I know of the effect on light of polarisers and analysers.		\odot		$\overline{\boldsymbol{\otimes}}$
12.3	I know that when a ray of unpolarised light is incident on the surface of an insulator at Brewster's angle the reflected ray becomes plane-polarised.		\odot	•	8
12.4	I can derive the relationship $n = \tan i_p$.		\odot		\odot
12.5	I can use an appropriate relationship to solve problems involving Brewster's angle and refractive index.		\odot		$\overline{\mathbf{S}}$
12.6	$n = \tan i_p$		\odot		$\overline{\mathbf{S}}$
ELECT	ROMAGNETISM				
Fields			\odot	\odot	
13.1	I know that an electric field is the region that surrounds electrically charged particles in which a force is exerted on other electrically charged particles.		\odot		\odot
13.2	I can define electric field strength as the electrical force acting on unit positive charge.		\odot		\odot
13.3	I can sketch electric field patterns around single point charges, a system of charges and a uniform electric field.		\odot		$\overline{\mathfrak{S}}$
13.4	I can define electrical potential at a point as the work done in moving unit positive charge from infinity to that point.		٢		\odot
13.5	I know that the energy required to move charge between two points in an electric field is independent of the path taken.		\odot		\odot
13.6	I can use appropriate relationships to solve problems involving electric force, electric potential and electric field strength, around a point charge and a system of charges.		Ü		$\overline{\mathbf{S}}$

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No		v x	Traf	fic Li	ght
13.7	$F = \frac{Q_1 Q_2}{4\pi\varepsilon_o r^2}$				
	$E = \frac{Q}{4\pi\varepsilon_o r^2}$		\odot		$\overline{\otimes}$
	$V = \frac{Q}{4\pi\varepsilon_o r}$				
13.8	I can use appropriate relationships to solve problems involving charge, energy, potential difference, and electric field strength, in situations involving a uniform electric field.		٢		$\overline{\mathfrak{S}}$
13.9	F = QE				
	V = Ed		\odot		$\overline{\mathbf{i}}$
	W = QV				
13.10	I know Millikan's experimental method for determining the charge on an electron.		\odot		$\overline{\otimes}$
13.11	I can use appropriate relationships to solve problems involving the motion of charged particles in uniform electric fields.		\odot		$\overline{\mathbf{S}}$
13.12	F = QE				
	V = Ed				
	W = QV		\odot		\otimes
	$E_k = \frac{1}{2} m v^2$				
13.13	I know that the electronvolt (eV) is the energy acquired when one electron accelerates through a potential difference of one volt.		٢		$\overline{\mathbf{S}}$
13.14	I can convert between electronvolts and joules		\odot		$\overline{\mathbf{i}}$
13.15	I know that electrons are in motion around atomic nuclei and individually produce a magnetic effect.		\odot		$\overline{\mathbf{S}}$

No			Traf	fic Li	ght
13.16	I know that, for example, iron, nickel, cobalt, and some rare earths exhibit a magnetic effect called ferromagnetism, in which magnetic dipoles can be made to align, resulting in the material becoming magnetised.		٢		3
13.17	I can sketch magnetic field patterns between magnetic poles, and around solenoids, including the magnetic field pattern around the Earth.			::	::
13.18	I can compare gravitational, electrostatic, magnetic and nuclear forces in terms of their relative strength and range.		\odot		\odot
13.19	I can use an appropriate relationship to solve problems involving magnetic induction around a current carrying wire, the current in the wire and the distance from the wire.		٢		©
13.20	$B = \frac{\mu_o I}{2\pi r}$		\odot		3
13.21	I can explain the helical path followed by a moving charged particle in a magnetic field.		\odot		\odot
13.22	I can use appropriate relationships to solve problems involving the forces acting on a current-carrying wire in a magnetic field and a charged particle in a magnetic field.		٢		<u>()</u>
13.23	$F = IlB\sin\theta$				
	$F = qvB$ $F = \frac{mv^2}{r}$		©		\odot
Circuit	ts		©	٢	
14.1	I know of the variation of current and potential difference with time in an RC circuit during charging and discharging.		\odot		\odot
14.2	I can define the time constant for an RC circuit as the time to increase the charge stored by 63% of the difference between initial charge and full charge, or the time taken to discharge the capacitor to 37% of initial charge		Ü		$\overline{\mathbf{S}}$

No		v x	Traf	fic Li	ght
14.3	I can use an appropriate relationship to determine the time constant for an RC circuit.		٢		\odot
14.4	$\tau = RC$		\odot		\odot
14.5	I know that, in an RC circuit, an uncharged capacitor can be considered to be fully charged after a time approximately equal to 5τ		٢		C:
14.6	I know that, in an RC circuit, a fully charged capacitor can be considered to be fully discharged after a time approximately equal to 5τ .		٢		÷
14.7	I can determine graphically the time constant for an RC circuit.		\odot		\odot
14.8	I know that capacitive reactance is the opposition of a capacitor to changing current		\odot		\odot
14.9	I can use appropriate relationships to solve problems involving capacitive reactance, voltage, current, frequency, and capacitance.		\odot		(<u>(</u>)
14.10	$X_{C} = \frac{V}{I}$ $X_{C} = \frac{1}{2\pi fC}$		٢	٢	3
14.11	I know of the growth and decay of current in a DC circuit containing an inductor		\odot		\odot
14.12	I can explain the self-inductance (inductance) of a coil.		\odot		\odot
14.3	I have knowledge of Lenz's law and its implications		\odot		\odot
14.4	I can define inductance and back EMF.		\odot		\odot
14.5	I know that energy is stored in the magnetic field around a current-carrying inductor.		\odot		\odot
14.6	I know of the variation of current with frequency in an AC circuit containing an inductor.		\odot		\odot

No			Traf	fic Li	ght
14.7	I know that inductive reactance is the opposition of an inductor to changing current.		\odot		\odot
14.8	I can use appropriate relationships to solve problems relating to inductive reactance, voltage, current, frequency, energy, and self-inductance (inductance).		٢		œ
14.9	$\mathcal{E} = -L \frac{dI}{dt}$ $E = \frac{1}{2}LI^{2}$ $X_{L} = \frac{V}{I}$ $X_{L} = 2\pi fL$:::	::	33
Electromagnetic radiation			\odot	::	\odot
15.1	I have a knowledge of the unification of electricity and magnetism.		\odot		\odot
15.2	I know that electromagnetic radiation exhibits wave properties as it transfers energy through space. It has both electric and magnetic field components which oscillate in phase, perpendicular to each other and to the direction of energy propagation.		٢	:	(j)
15.3	I can use an appropriate relationship to solve problems involving the speed of light, the permittivity of free space and the permeability of free space.				3
15.4	$c = \frac{1}{\sqrt{\varepsilon_o \mu_o}}$		©		\odot
UNITS, PREFIXES AND UNCERTAINTIES					
Units,	prefixes and scientific notation		\odot		\odot
16.1	I can make appropriate use of units, including electronvolt (eV), light year (ly) and astronomical unit (AU).		\odot		\odot

No			Traf	fic Li	ght
16.2	I can use SI units with all physical quantities where appropriate.		\odot		\odot
16.3	I can use prefixes where appropriate. These include femto (f), pico (p), nano (n), micro (μ), milli (m), kilo (k), mega (M), giga (G), tera (T), and peta (P)		٢		3
16.4	I can use the appropriate number of significant figures in final answers. This means that the final answer can have no more significant figures than the data with fewest number of significant figures used in the calculation.		٢		3
16.5	I can make appropriate use of scientific notation		\odot		\odot
Uncertainties			\odot		$\overline{\mathbf{i}}$
17.1	I know and can use uncertainties, including systematic uncertainties, scale reading uncertainties, random uncertainties, and calibration uncertainties.		٢		3
17.2	I know systematic uncertainty occurs when readings taken are either all too small or all too large. This can arise due to measurement techniques or experimental design		٢		3
17.3	I know a scale reading uncertainty is an indication of how precisely an instrument scale can be read		\odot		\odot
17.4	I know random uncertainty arises when measurements are repeated and slight variations occur. Random uncertainty may be reduced by increasing the number of repeated measurements.		٢		3
17.5	I know calibration uncertainty arises when there is a difference between a manufacturer's claim for the accuracy of an instrument compared with an approved standard.		٢		\odot
17.6	I can solve problems involving absolute uncertainties and fractional/percentage uncertainties				$\overline{\mathfrak{S}}$
17.7	I can make appropriate use of significant figures in absolute uncertainties.		\odot		\odot

No			Traf	fic Li	ght
17.8	Absolute uncertainty should be rounded to one significant figure. In some instances a second significant figures may be retained (if the absolute uncertainty is small).		٢		÷
Data an	alysis		\odot		\odot
18.1	I can combine various types of uncertainties to obtain the total uncertainty in a measurement.		\odot		\odot
18.2	I know that, when uncertainties in a single measurement are combined, an uncertainty can be ignored if it is less than one third of one of the other uncertainties in the measurement.		\odot	:	3
18.3	I can use an appropriate relationship to determine the total uncertainty in a measured value.		\odot		\odot
18.4	$\Delta W = \sqrt{\Delta X^2 + \Delta Y^2 + \Delta Z^2}$		\odot		\odot
18.5	I can combine uncertainties in measured values to obtain the total uncertainty in a calculated value		٢		\odot
18.6	I know that, when uncertainties in measured values are combined, a fractional/percentage uncertainty in a measured value can be ignored if it is less than one third of the fractional/percentage uncertainty in another measured value.		٢	:	(\mathbf{i})
18.7	I can use an appropriate relationship to determine the total uncertainty in a value calculated from the product or quotient of measured values.		٢		(j)
18.8	$\frac{\Delta W}{W} = \sqrt{\left(\frac{\Delta X}{X}\right)^2 + \left(\frac{\Delta Y}{Y}\right)^2 + \left(\frac{\Delta Z}{Z}\right)^2}$		٢		3
18.9	I can use an appropriate relationship to determine the uncertainty in a value raised to a power.				\odot
18.10	$\left(\frac{\Delta W^n}{W^n}\right) = n\left(\frac{\Delta W}{W}\right)$		\odot		$\overline{\mathbf{S}}$
18.11	I can use error bars to represent absolute uncertainties on graphs.		٢		\odot

No 🗸		Traffic Light			
18.12	I can estimate uncertainty in the gradient and intercept of the line of best fit on a graph.		\odot		\odot
18.13	I can correctly use the terms accuracy and precision in the context of an evaluation of experimental results. The accuracy of a measurement compares how close the measurement is to the 'true' or accepted value. The precision of a measurement gives an indication of the uncertainty in the measurement.		٢	:	\odot
Data analysis		\odot		8	
19.1	I can identify the dominant uncertainty/uncertainties in an experiment or in experimental data.				
19.2	I can suggest potential improvements to an experiment, which may reduce the dominant uncertainty/uncertainties.				

Course assessment structure: project

Project 30 marks

The project has 30 marks. This is scaled by SQA to represent 25% of the overall marks.

The purpose of the project is to allow you to carry out an in-depth investigation of a physics topic and produce a project report. You are required to plan and carry out a physics investigation.

You should keep a record of their work (daybook) as this will form the basis of your project report. This record should include details of your research, experiments and recorded data.

It gives you an opportunity to demonstrate the following skills, knowledge and understanding:

- extending and applying knowledge of physics to new situations, interpreting and analysing information to solve more complex problems
- planning and designing physics experiments/investigations, using reference material, to test a hypothesis or to illustrate particular effects
- recording systematic detailed observations and collecting data
- selecting information from a variety of sources
- presenting detailed information appropriately in a variety of forms
- processing and analysing physics data (using calculations, significant figures and units, where appropriate)
- making reasoned predictions from a range of evidence/information
- drawing valid conclusions and giving explanations supported by evidence/justification
- critically evaluating experimental procedures by identifying sources of uncertainty, and suggesting and implementing improvements
- drawing on knowledge and understanding of physics to make accurate statements, describe complex information, provide detailed explanations, and integrate knowledge
- communicating physics findings/information fully and effectively
- analysing and evaluating scientific publications and media reports

Project overview

Candidates carry out an in-depth investigation of a physics topic. Candidates choose their topic and individually investigate/research its underlying physics. Candidates must discuss potential topics with their teacher and/or lecturer to ensure that they do not waste time researching unsuitable topics. This is an open-ended task that may involve candidates carrying out a significant part of the work without supervision.

Section	Expected response	Mark allocation
Abstract	A brief abstract (summary) stating the overall aim and findings/conclusion(s) of the project.	1
Underlying physics	 A description of the underlying physics that: is relevant to the project demonstrates an understanding of the physics theory underpinning the project is of an appropriate level and commensurate with the demands of Advanced Higher Physics 	4
Procedures	Labelled diagrams and/or descriptions of apparatus, as appropriate	2
Clear descriptions of how the apparatus was used to obtain experimental readings.		2
	 Procedures are at an appropriate level of complexity and demand. Factors to be considered include: range of procedures control of variables accuracy and precision originality of approach and/or experimental techniques degree of sophistication of experimental design and/or equipment 	3
Results (including	Data is sufficient and relevant to the aim of the project.	1
uncertainties) Appropriate analysis of data, for example, quality of graphs, lines of best fit, calculations.		4
	Uncertainties in individual readings and final results.	3
Discussion (conclusion(s) and	Valid conclusion(s) that relate to the aim of the project	1
evaluation)	 Evaluations of experimental procedures to include, as appropriate, comment on: accuracy and precision of experimental measurements adequacy of repeated readings adequacy of range over which variables are altered adequacy of control of variables limitations of equipment reliability of methods sources of uncertainties 	3
	 Coherent discussion of overall conclusion(s) and critical evaluation of the project as a whole, to include, as appropriate, comment on: selection of procedures problems encountered during planning modifications to planned procedures interpretation and significance of findings suggestions for further improvements to procedures suggestions for further work 	3

Section	Expected response	Mark allocation
	A report which indicates a quality project.	1
Presentation Appropriate structure, including informative title, contents page and page numbers.		1
	References cited in the text and listed at an appropriate point in the report. Citing and listing using either Vancouver or Harvard referencing system.	1
Total		30